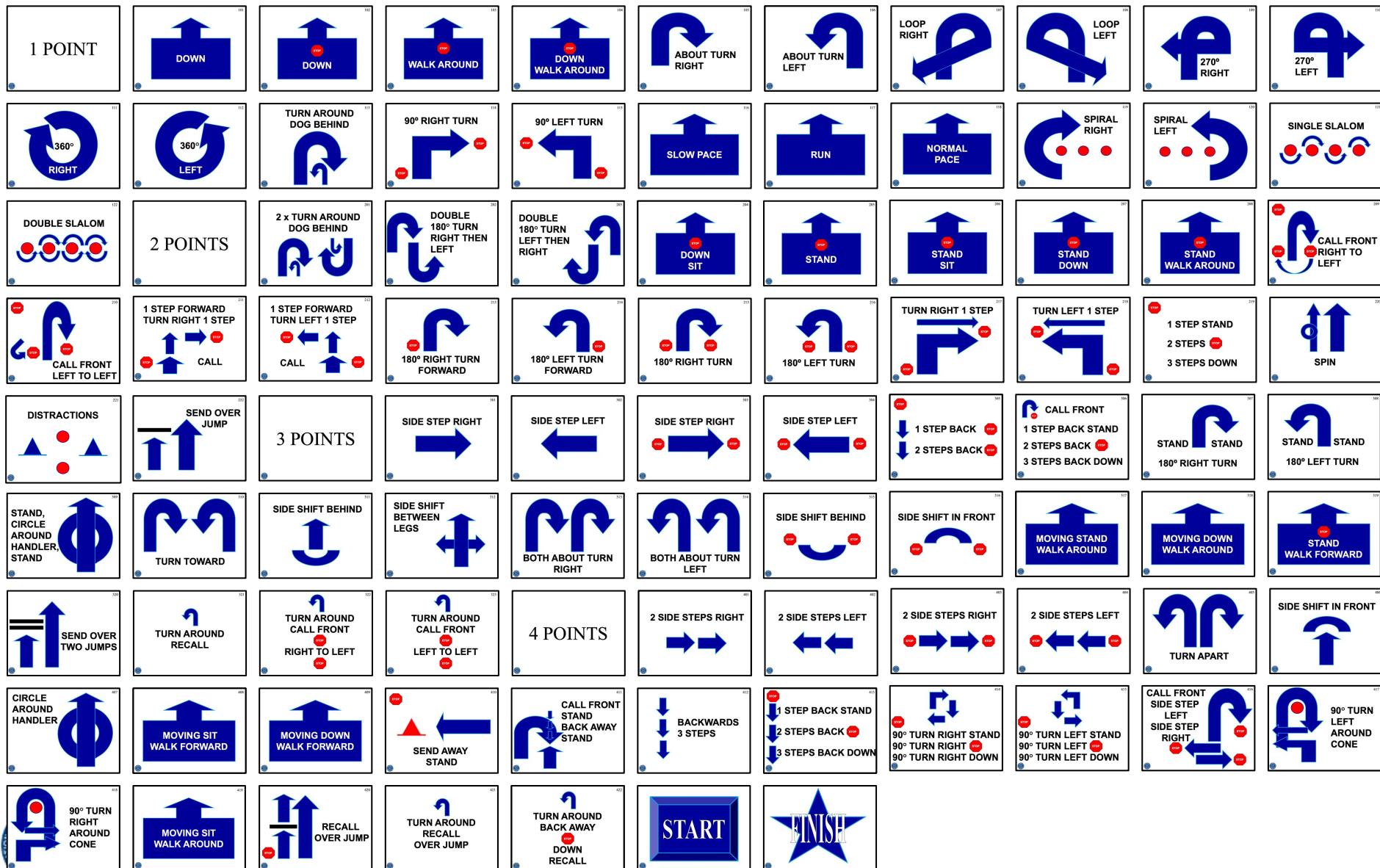
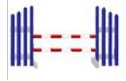


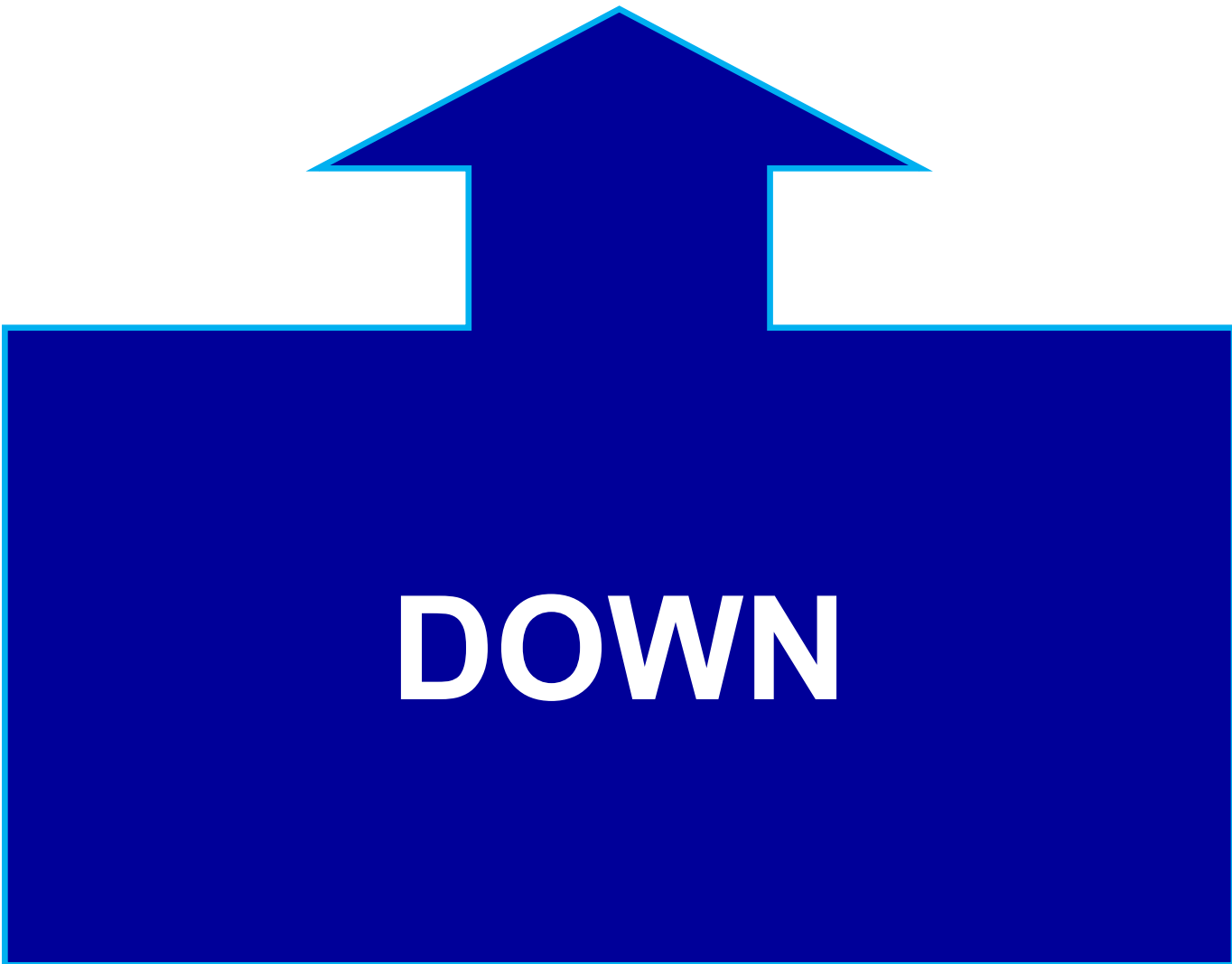
FCI Exercises



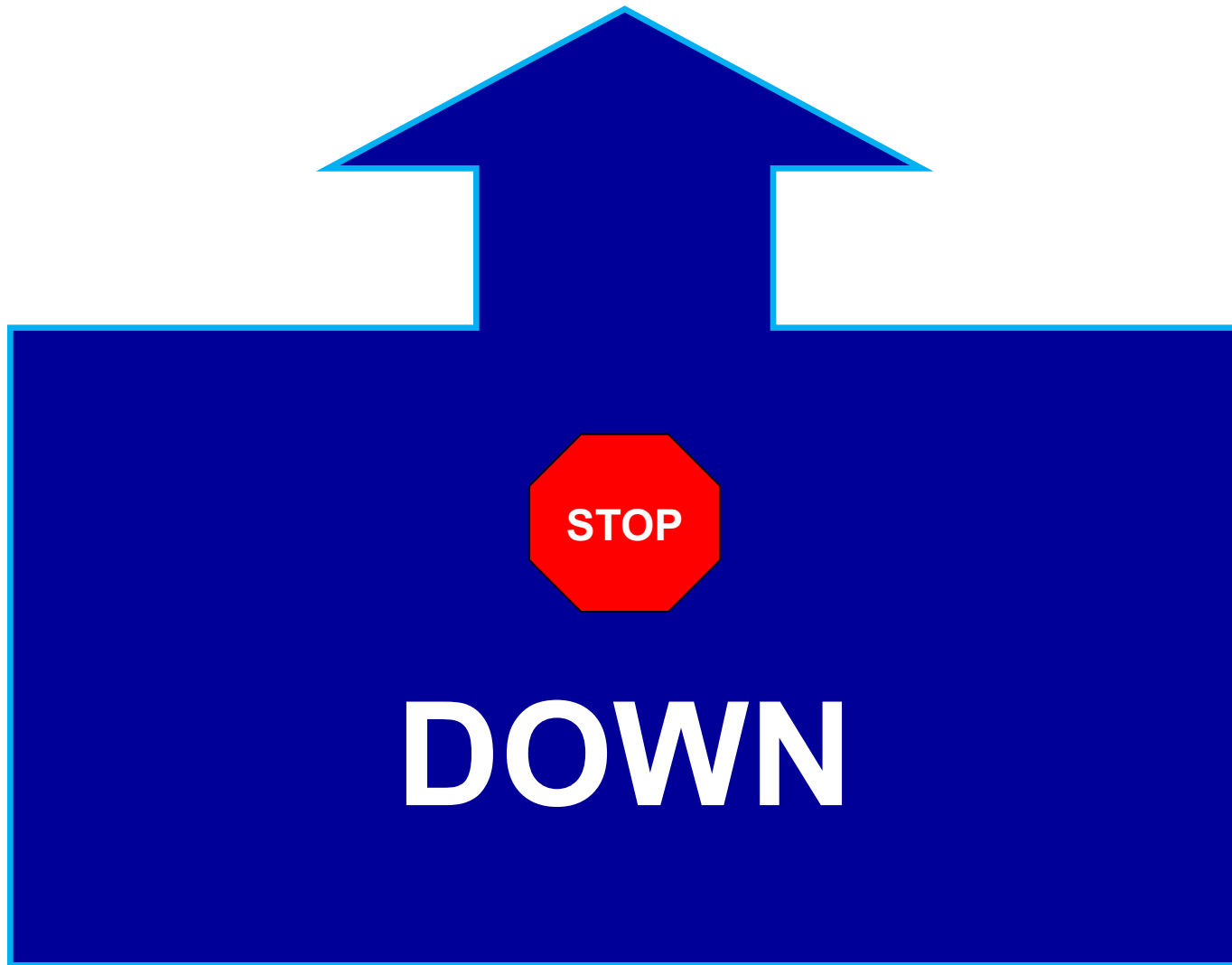
START

FINISH

1 POINT



DOWN

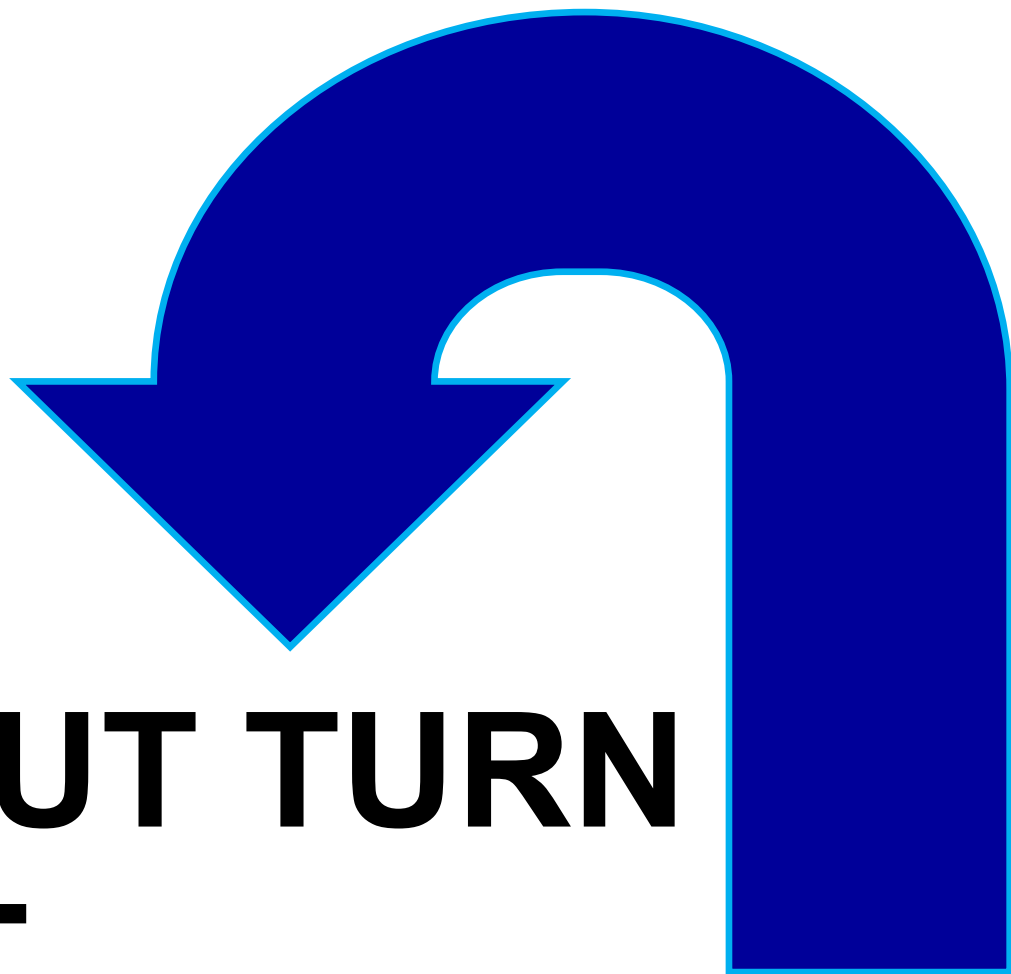








**ABOUT TURN
RIGHT**



**ABOUT TURN
LEFT**

LOOP RIGHT

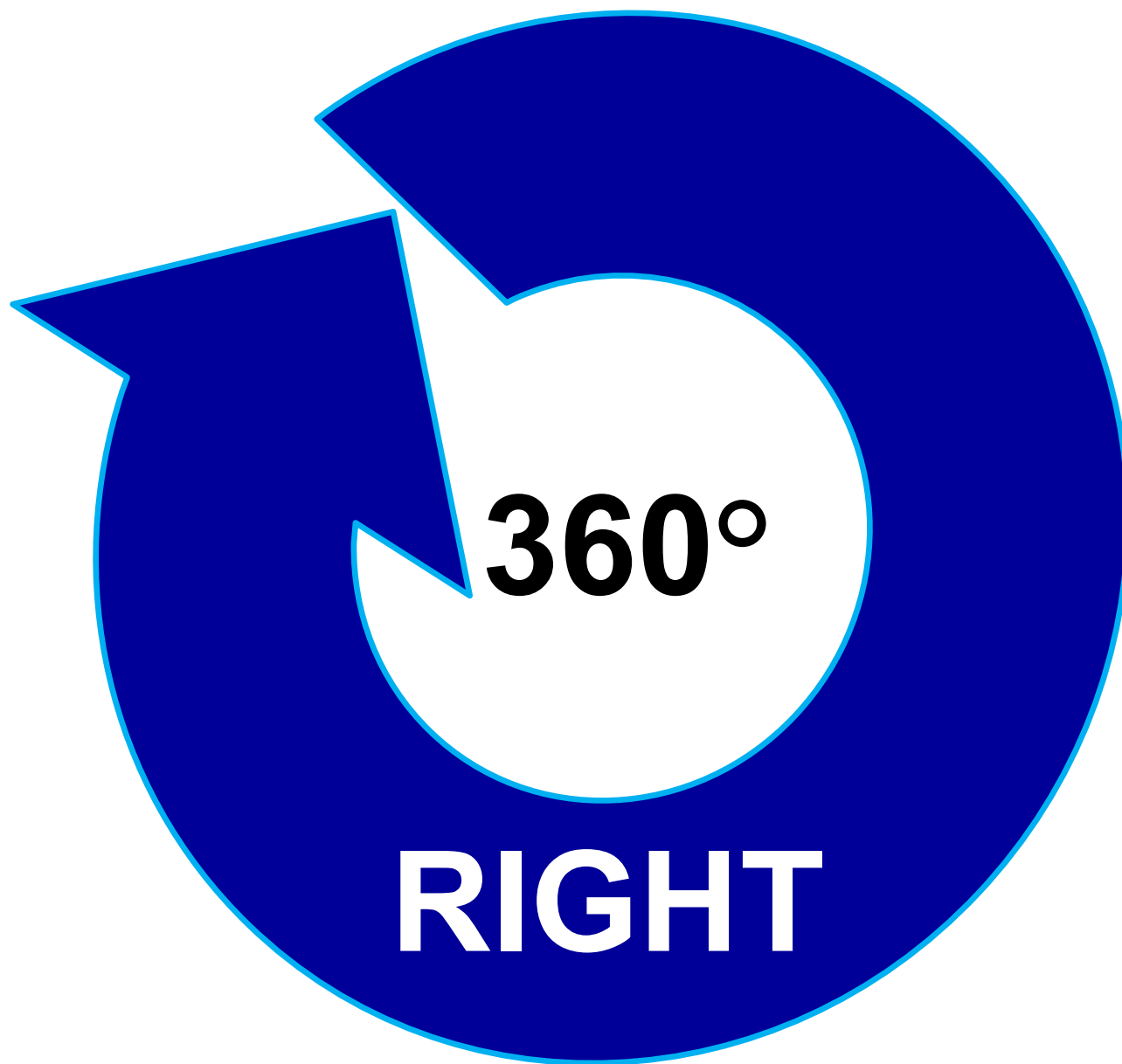


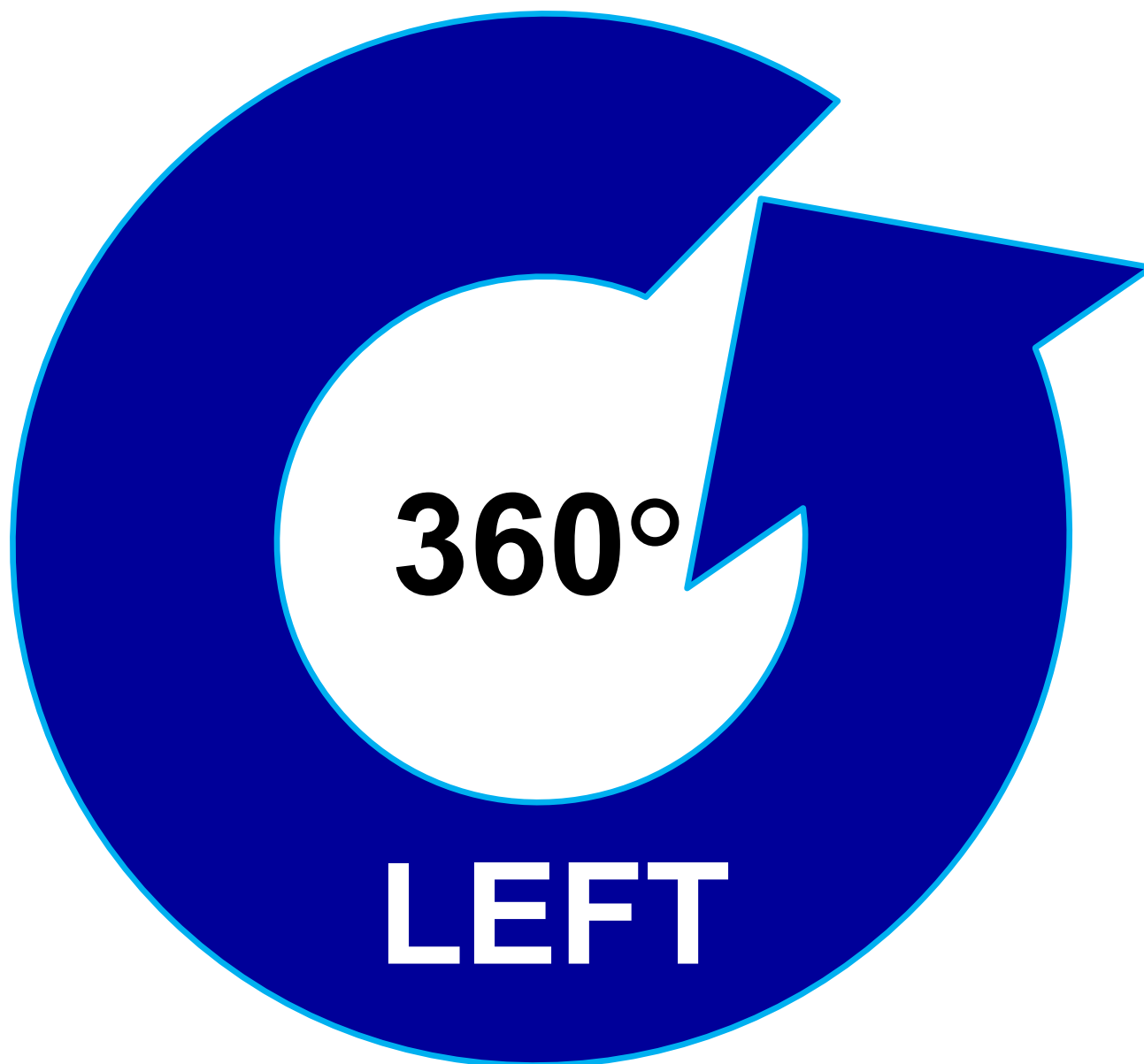
**LOOP
LEFT**



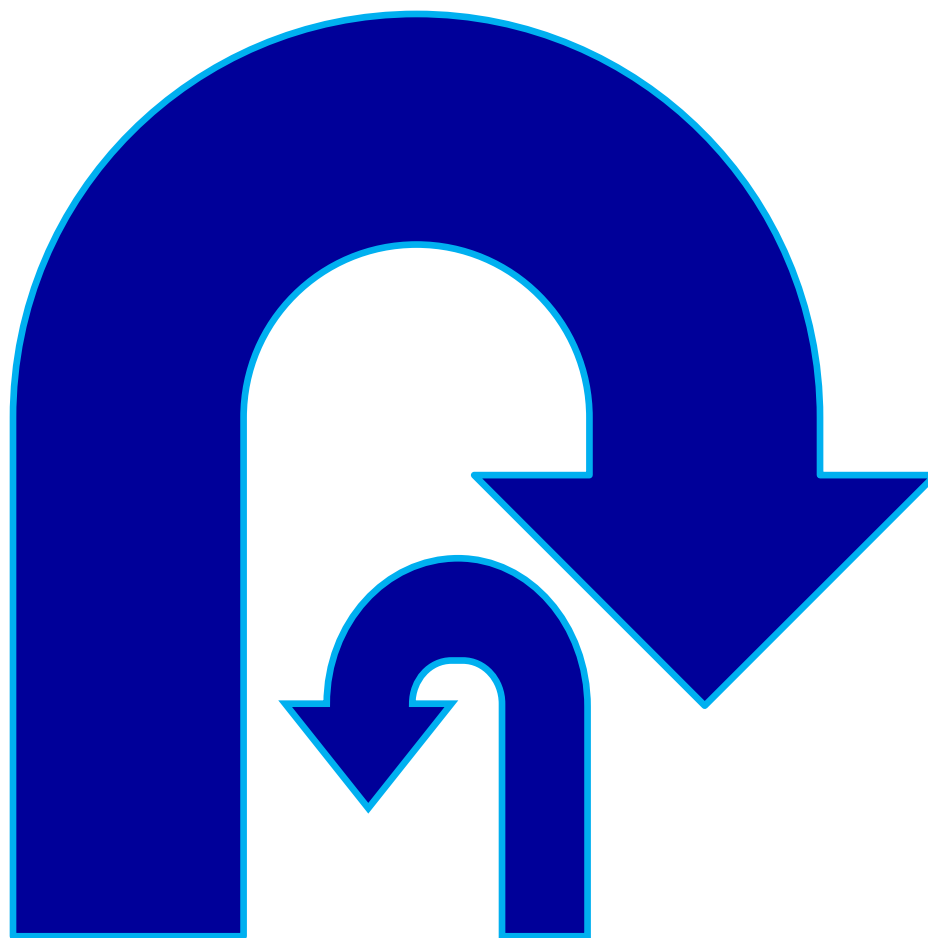




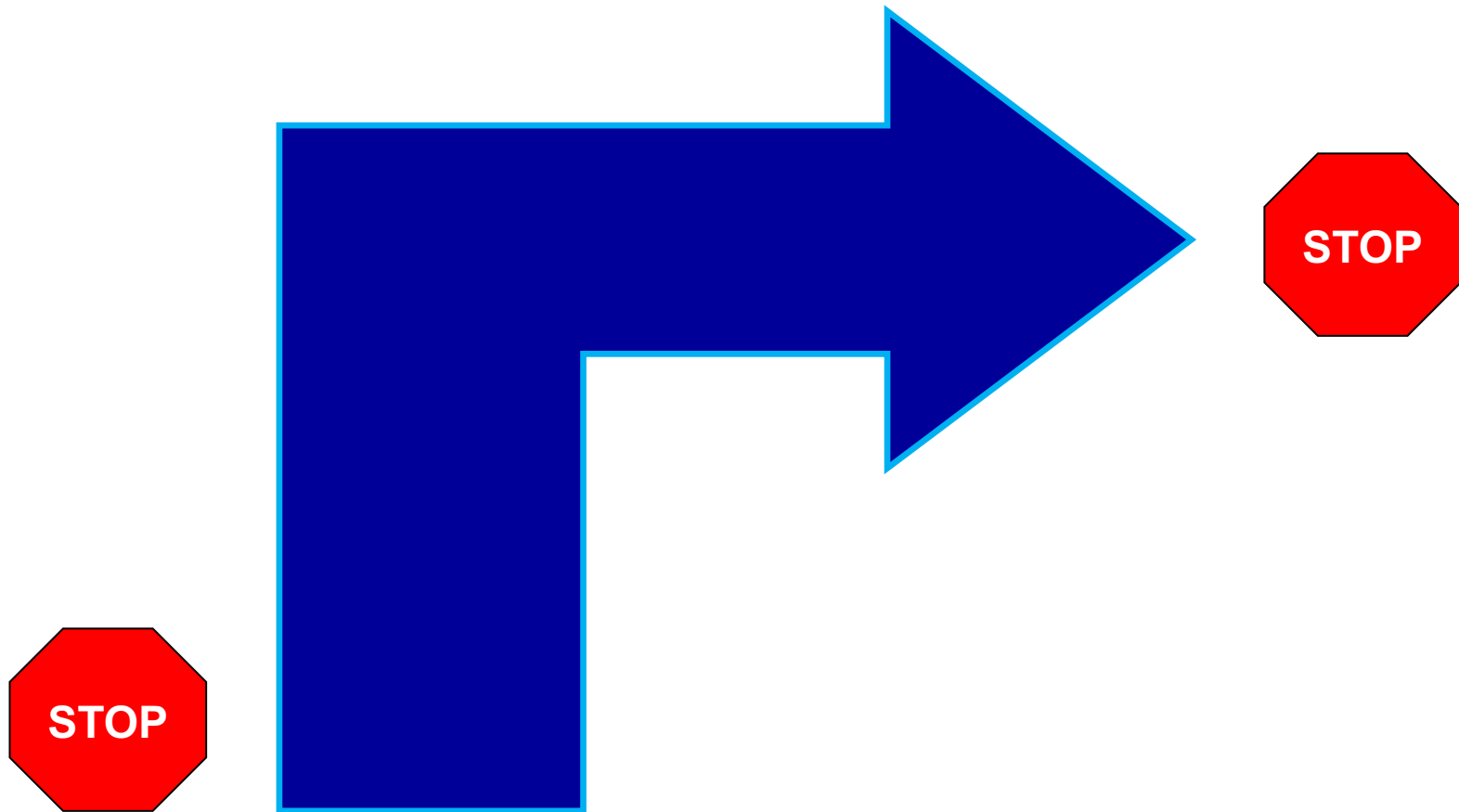




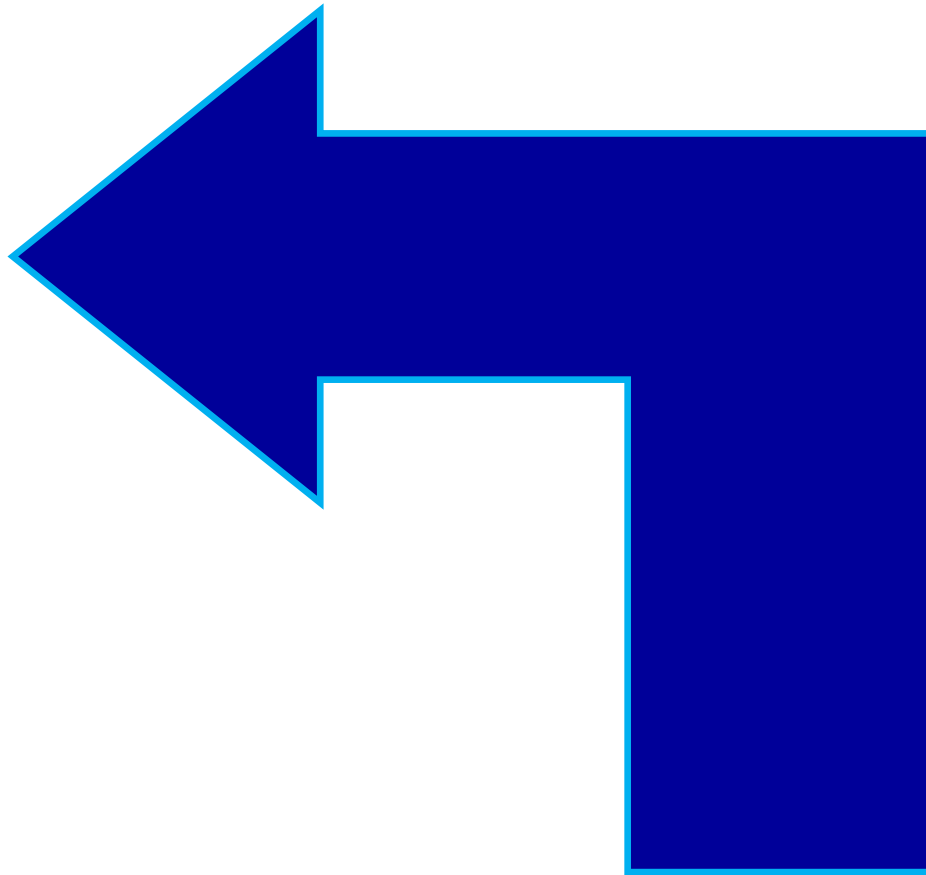
TURN AROUND DOG BEHIND



90° RIGHT TURN



90° LEFT TURN





SLOW PACE

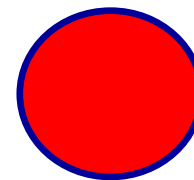
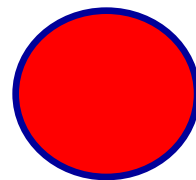
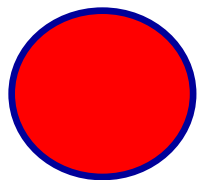
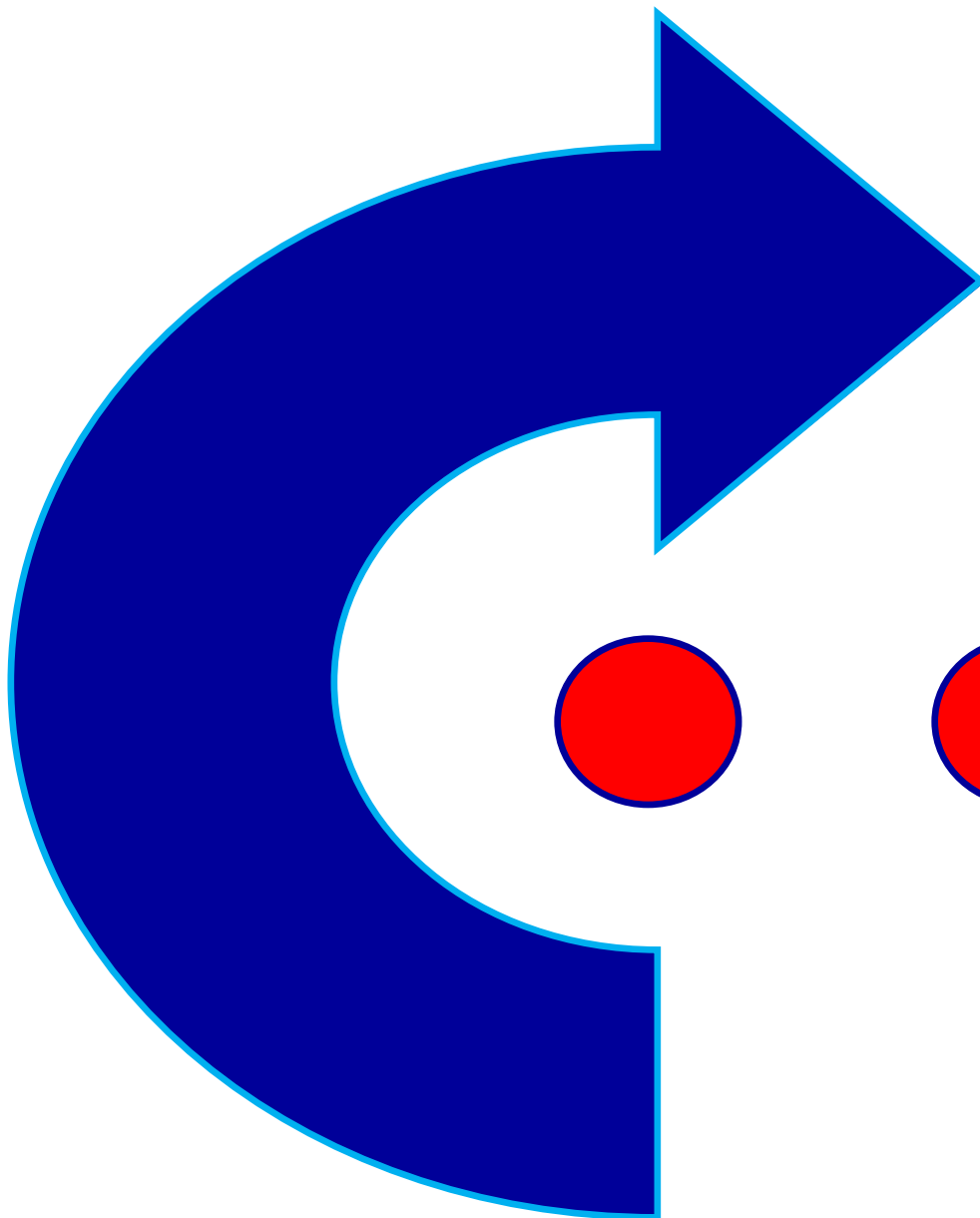


RUN

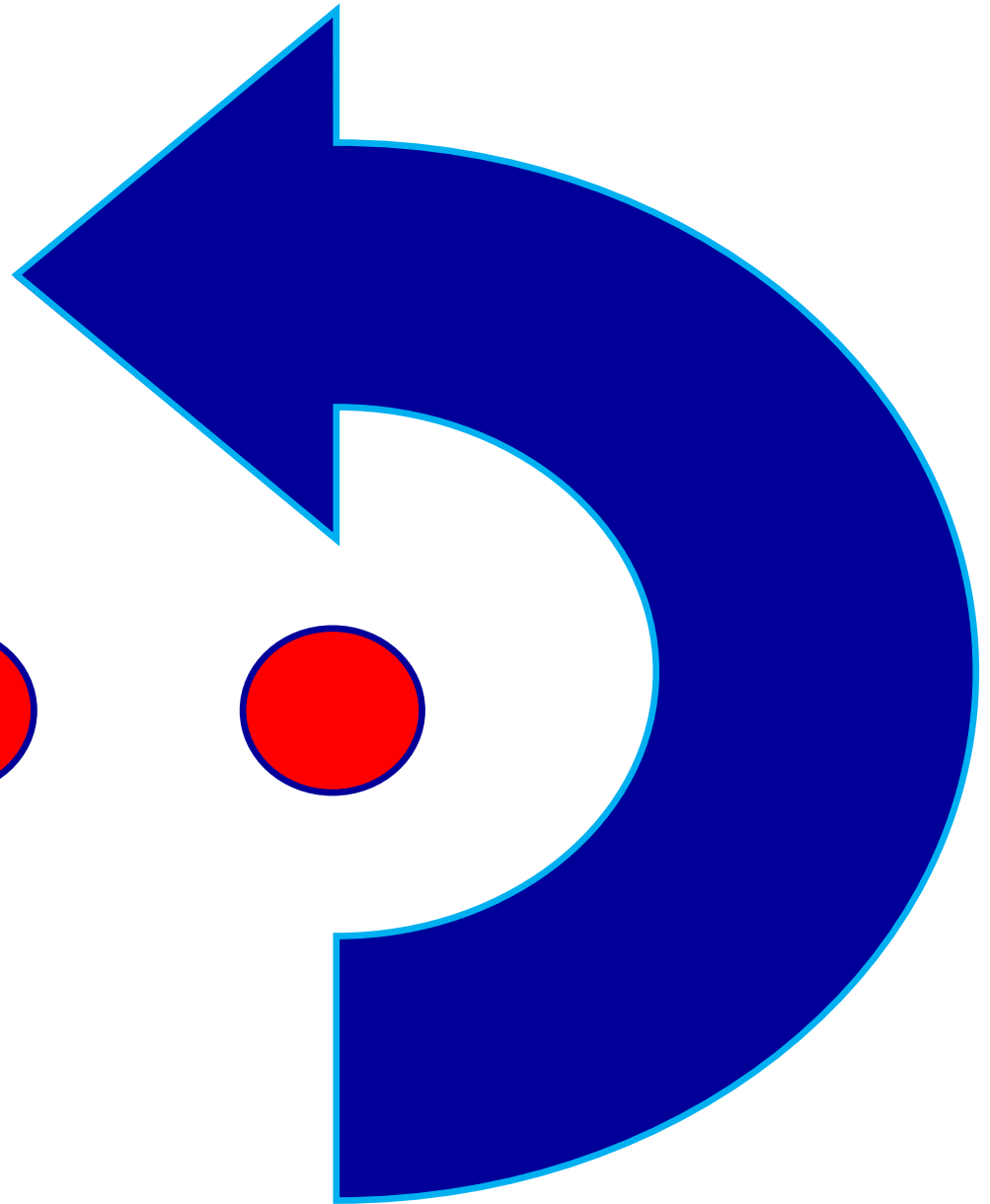
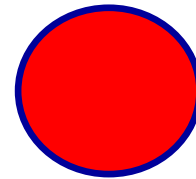
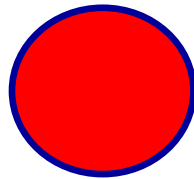
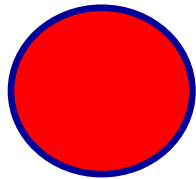


**NORMAL
PACE**

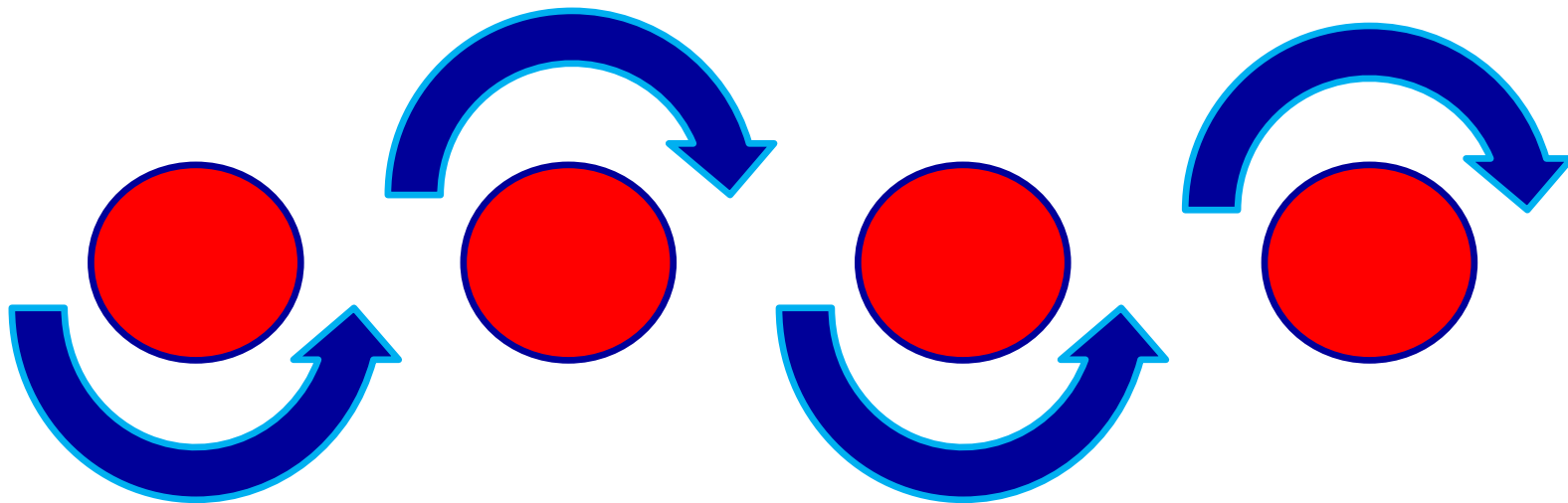
SPIRAL RIGHT



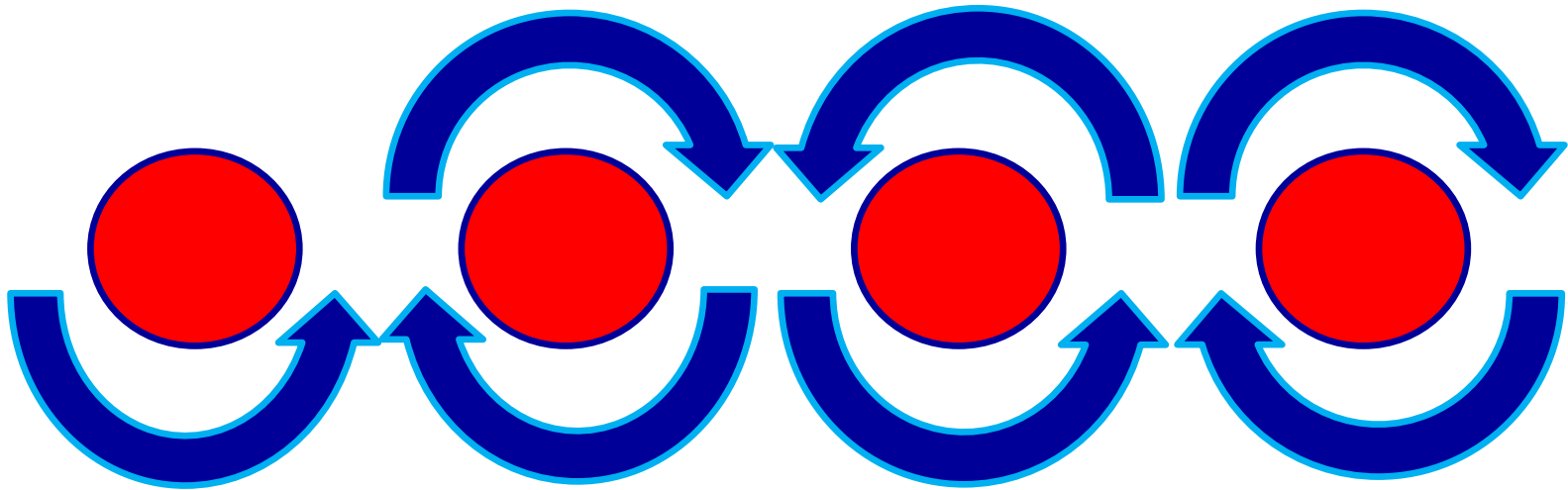
SPIRAL LEFT



SINGLE SLALOM

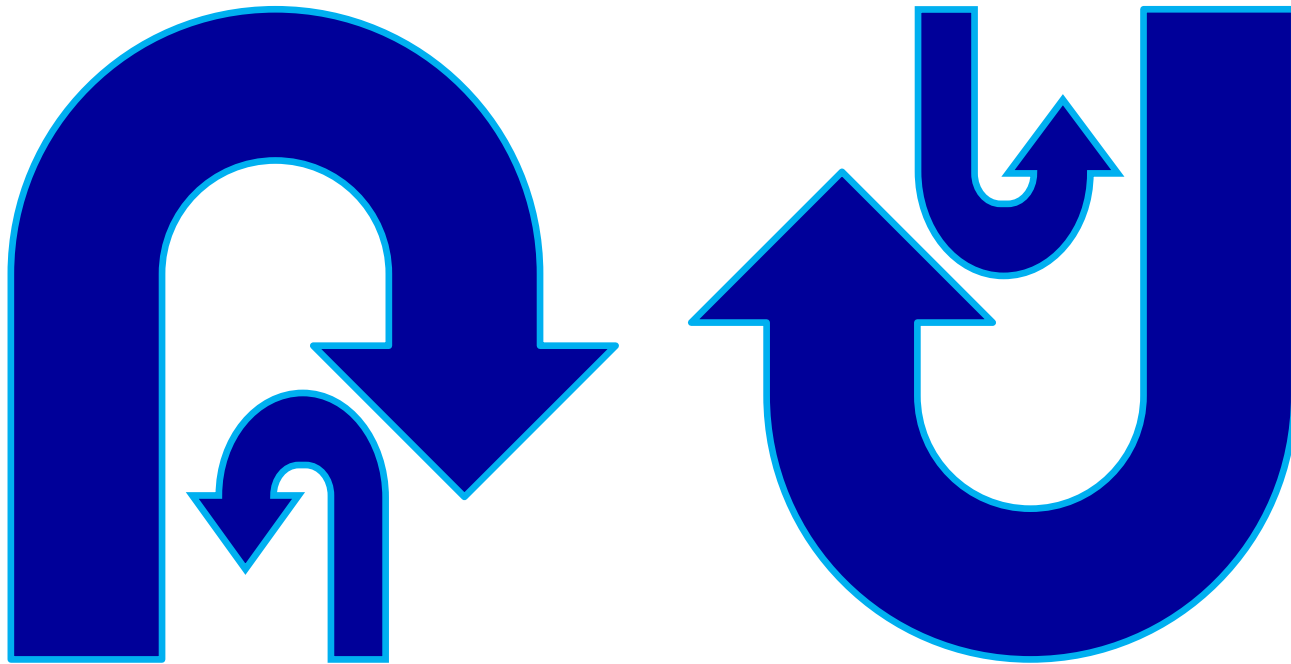


DOUBLE SLALOM



2 POINTS

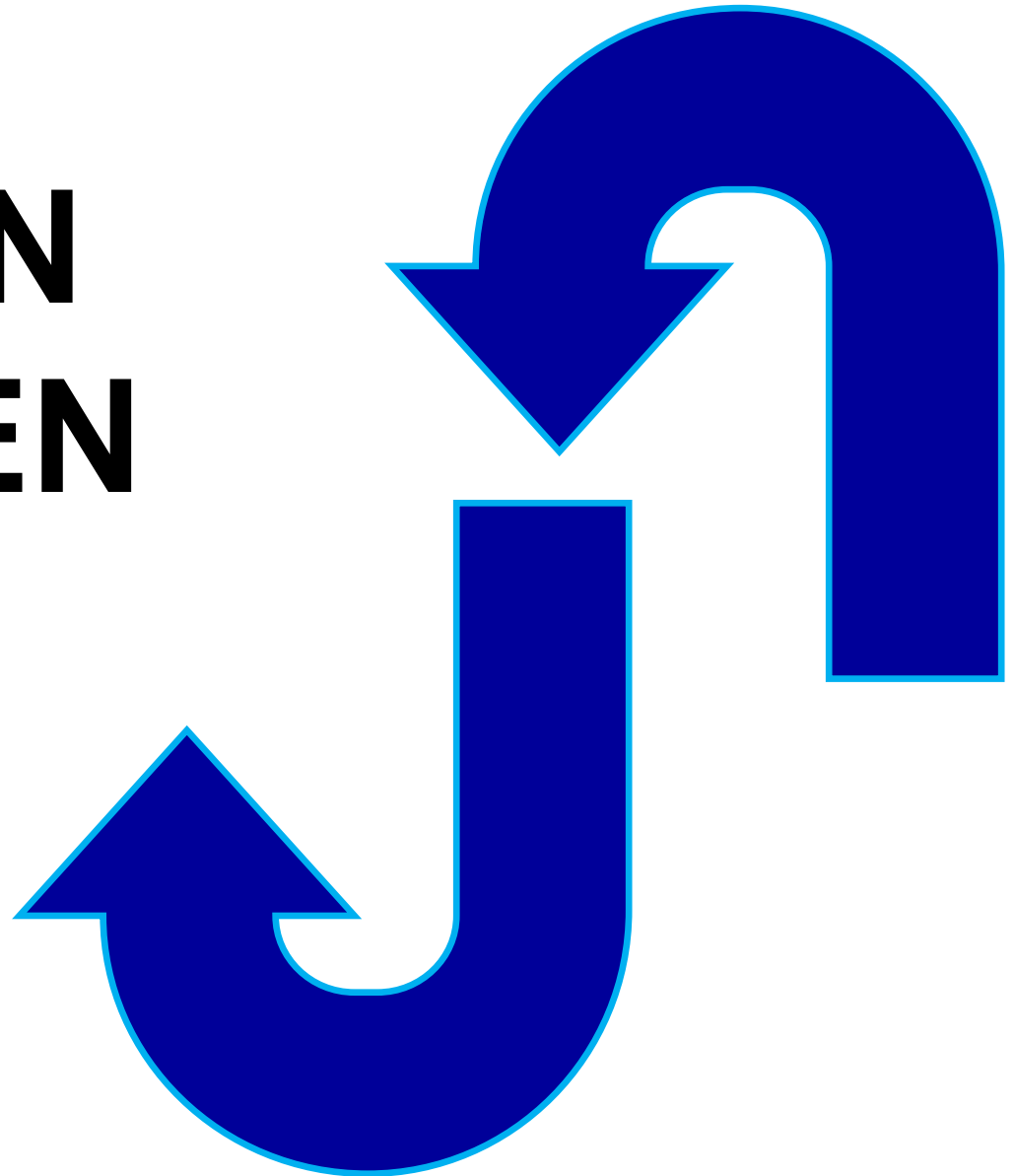
2 x TURN AROUND DOG BEHIND

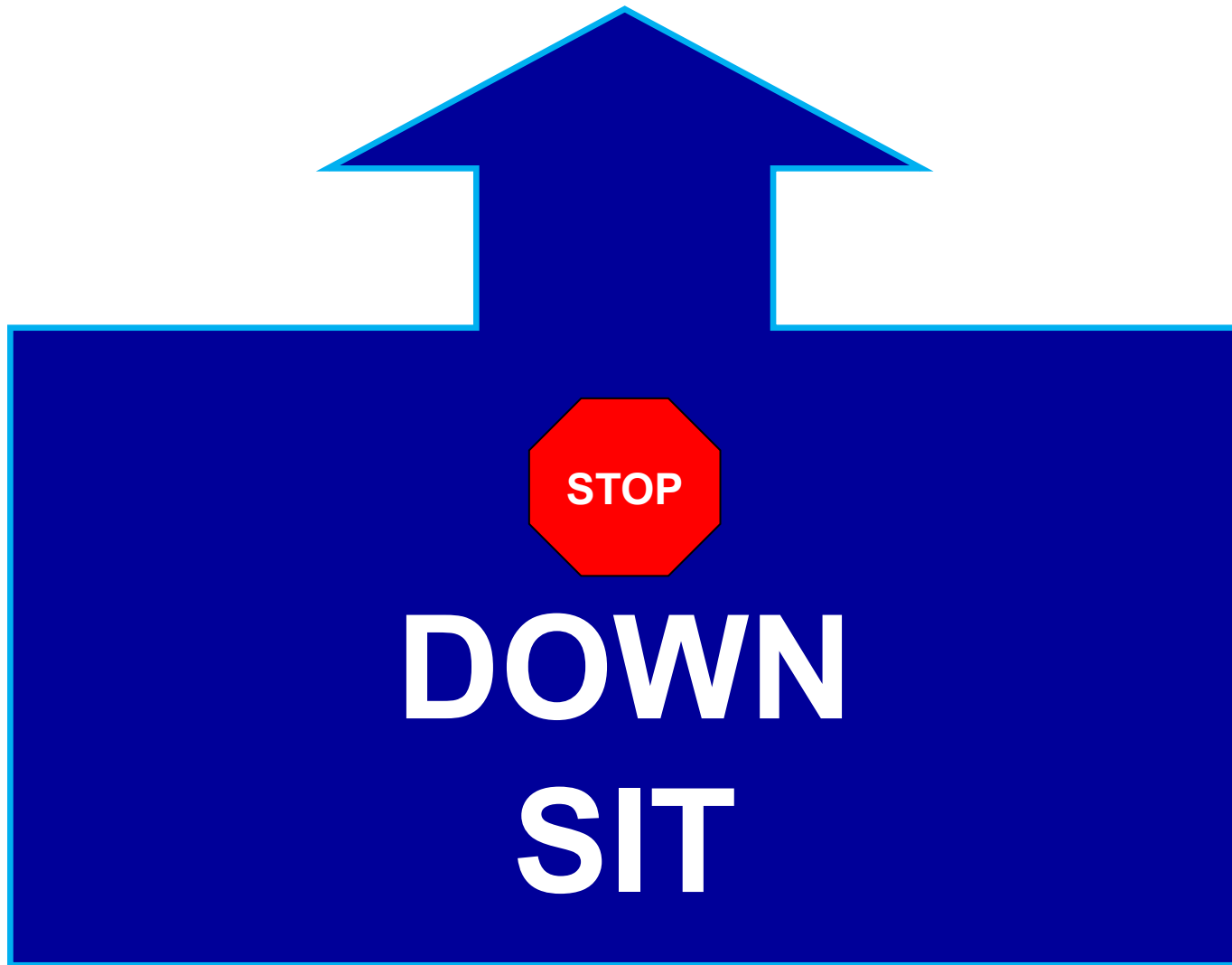


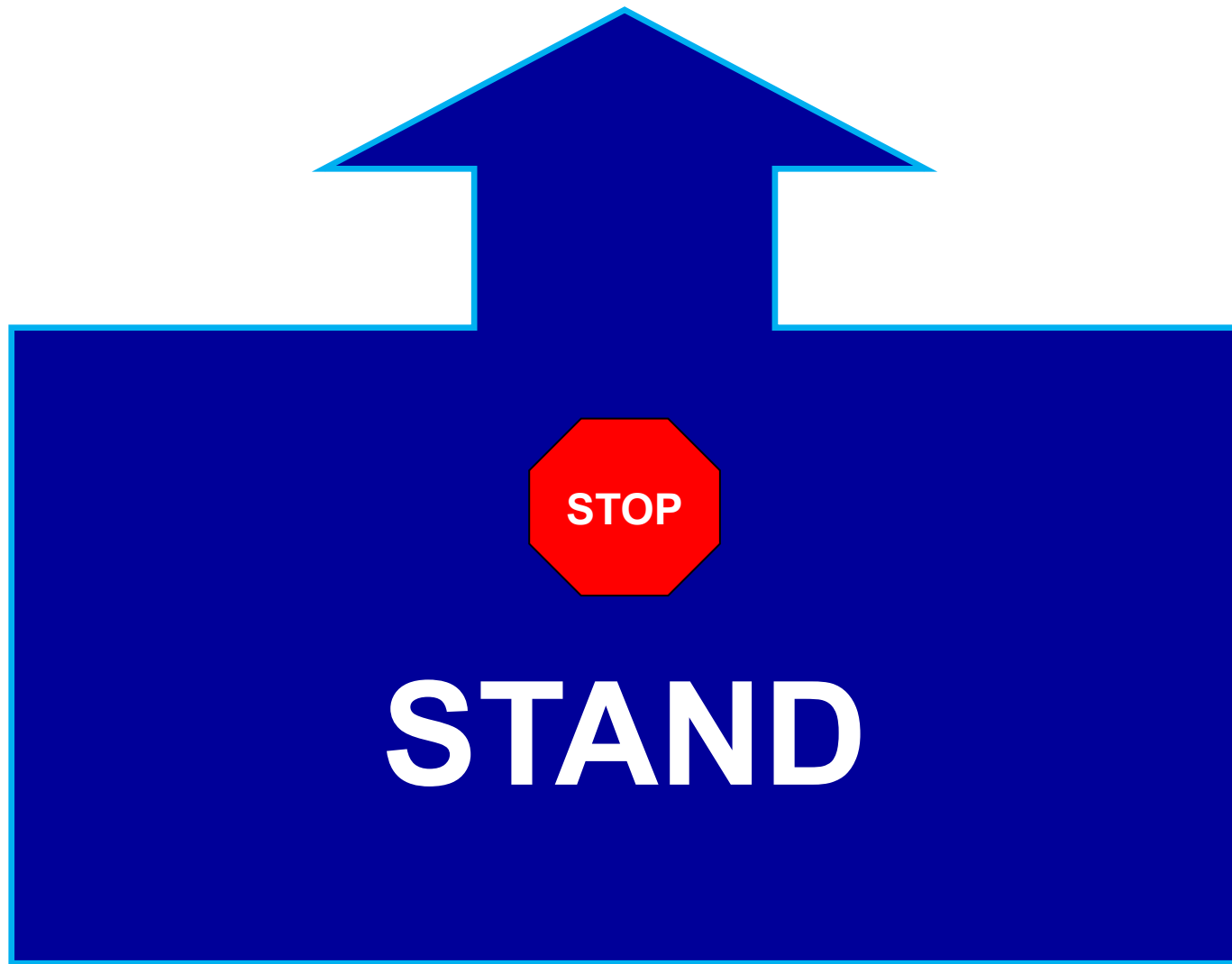
**DOUBLE
180° TURN
RIGHT THEN
LEFT**

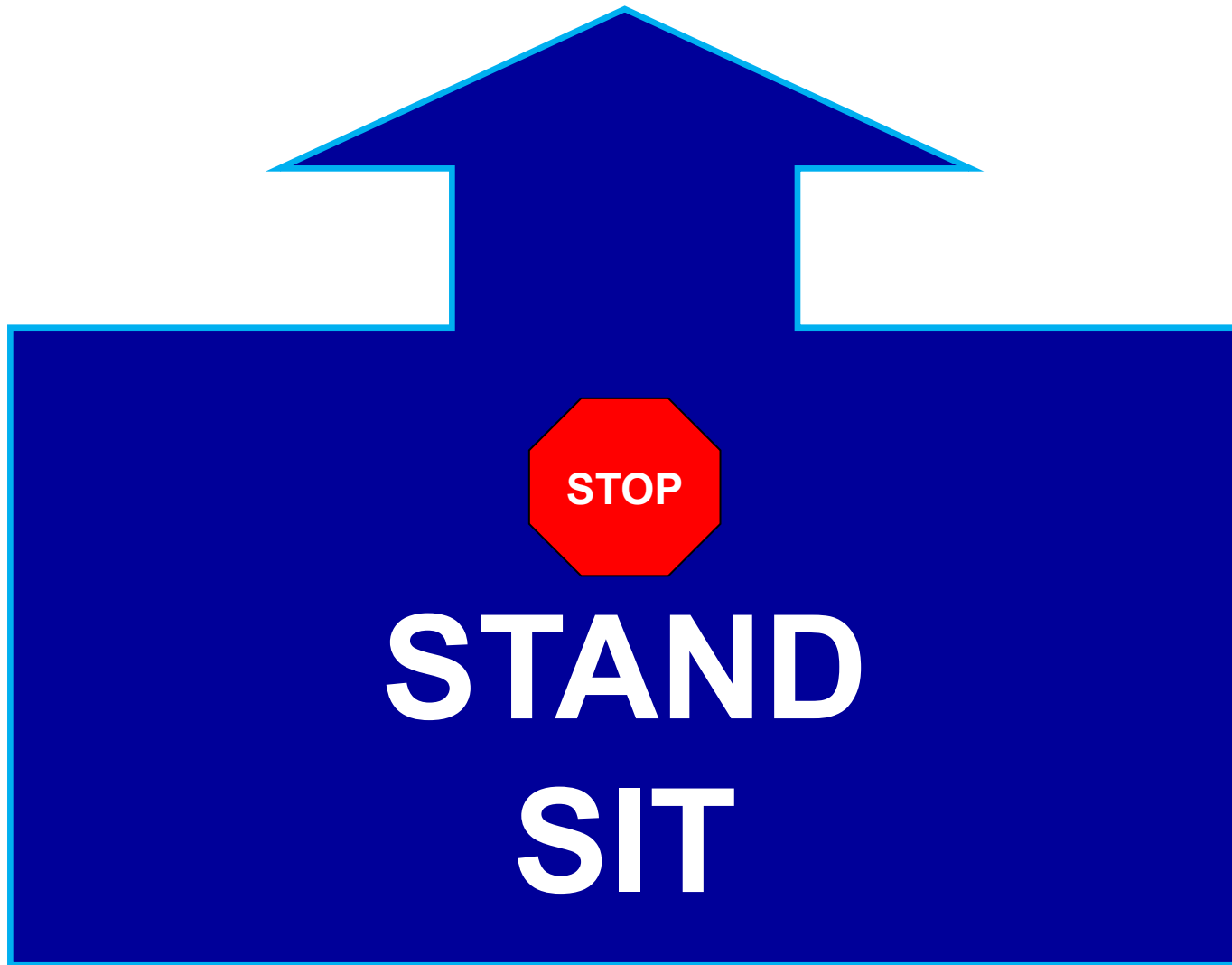


**DOUBLE
180° TURN
LEFT THEN
RIGHT**



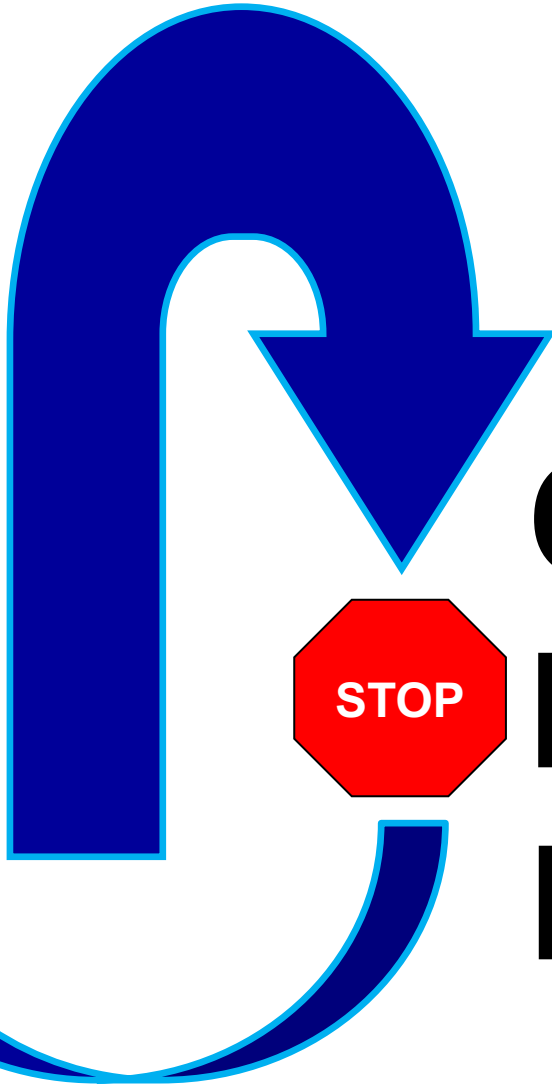
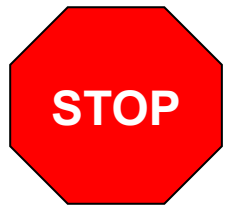




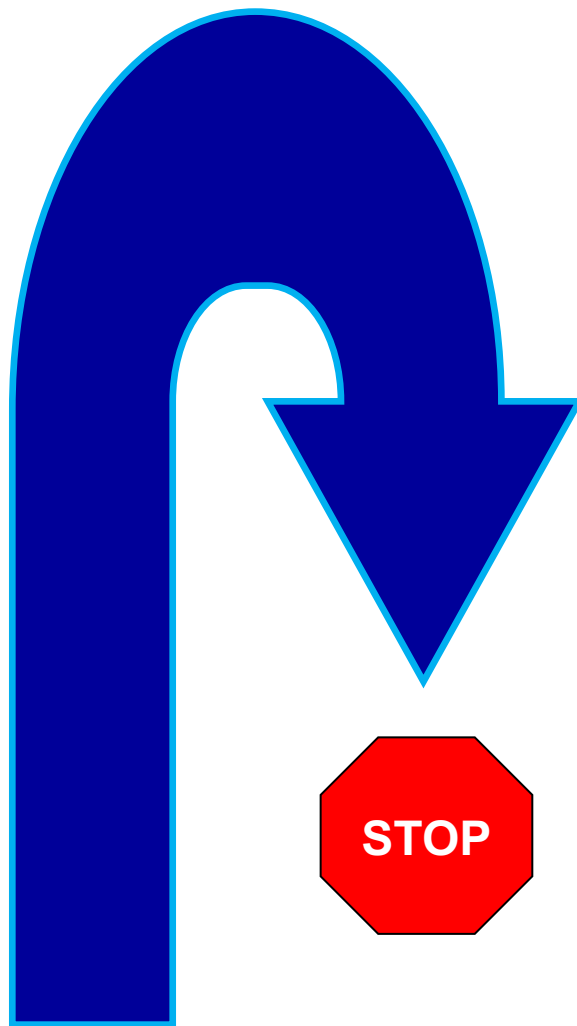






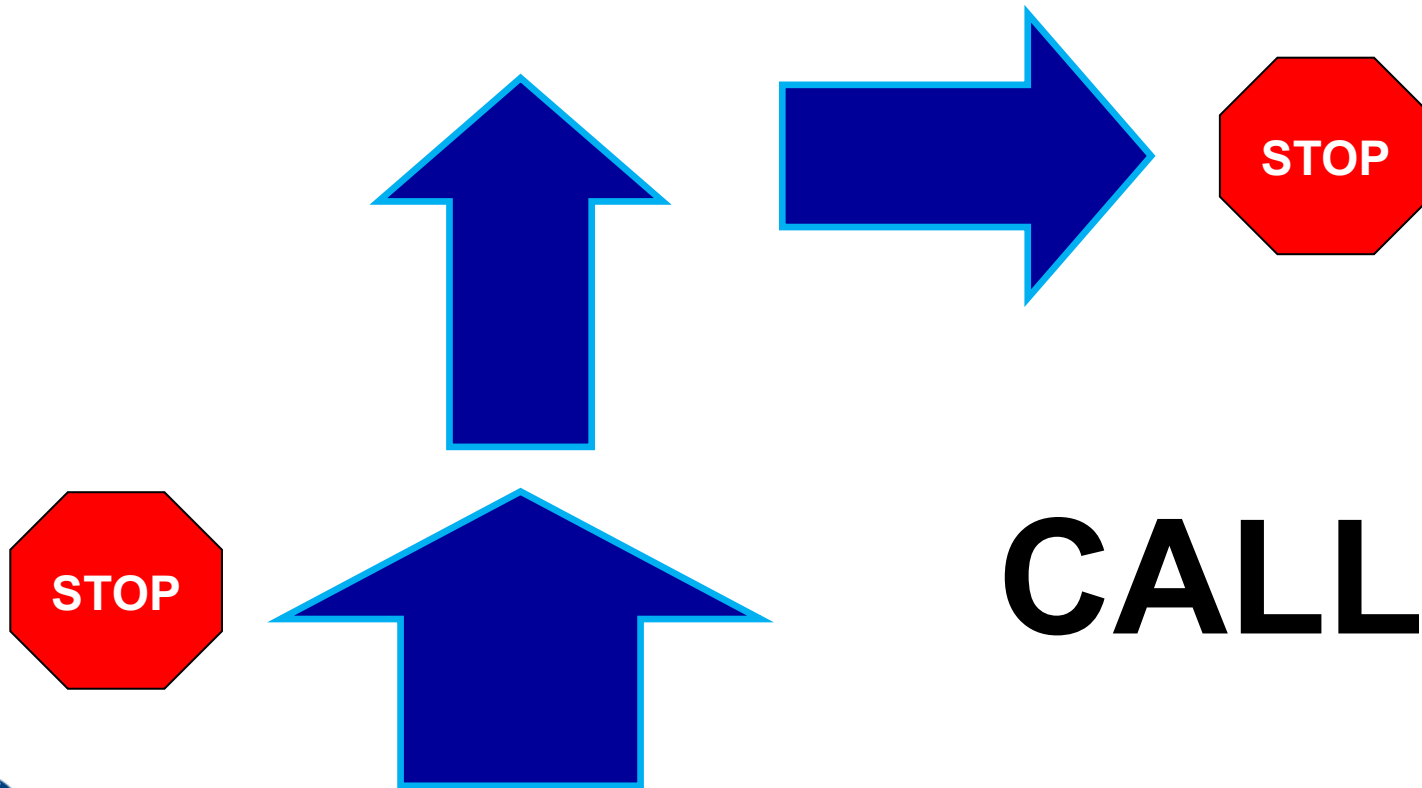


**CALL FRONT
RIGHT TO
LEFT**

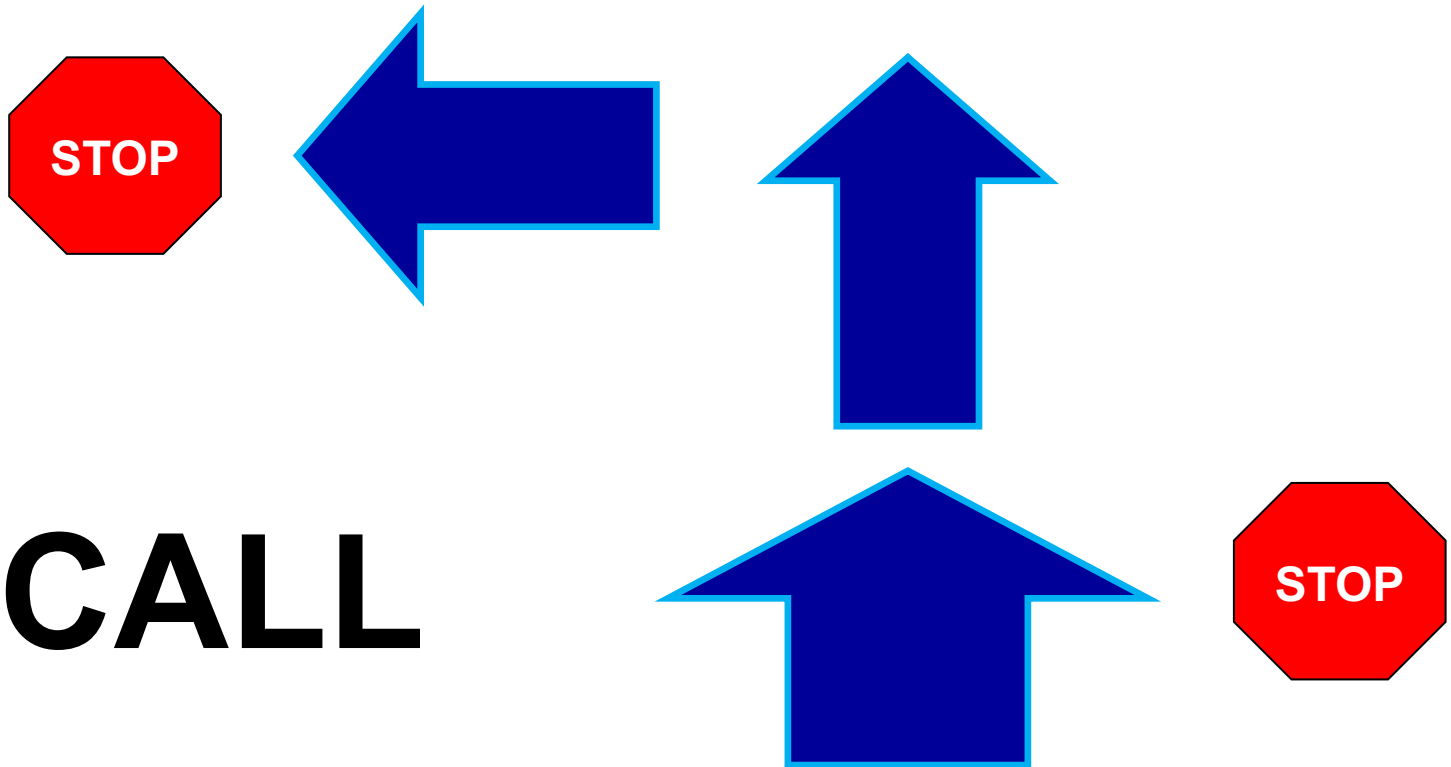


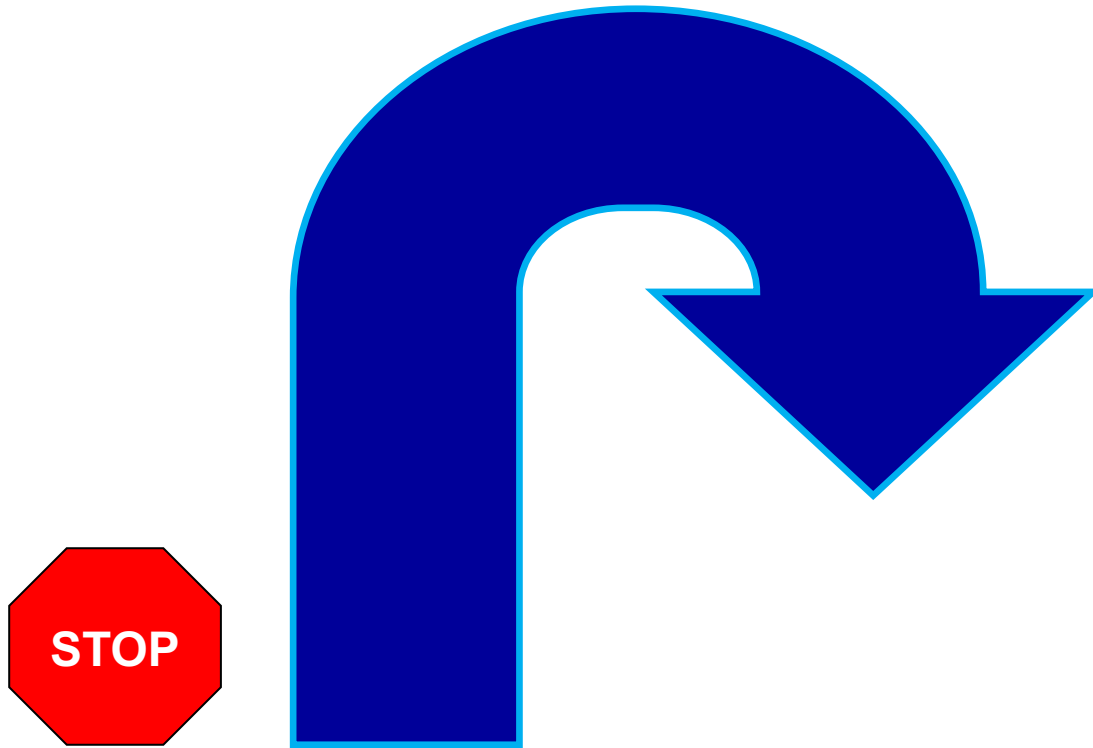
**CALL FRONT
LEFT TO LEFT**

1 STEP FORWARD TURN RIGHT 1 STEP

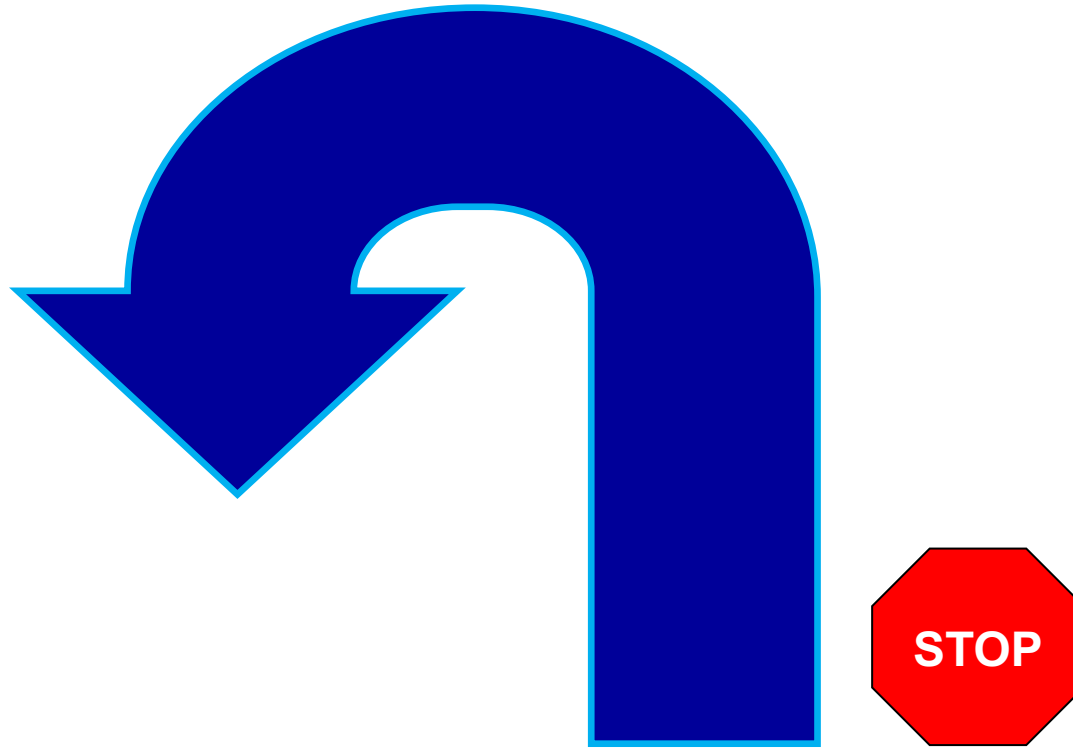


1 STEP FORWARD TURN LEFT 1 STEP

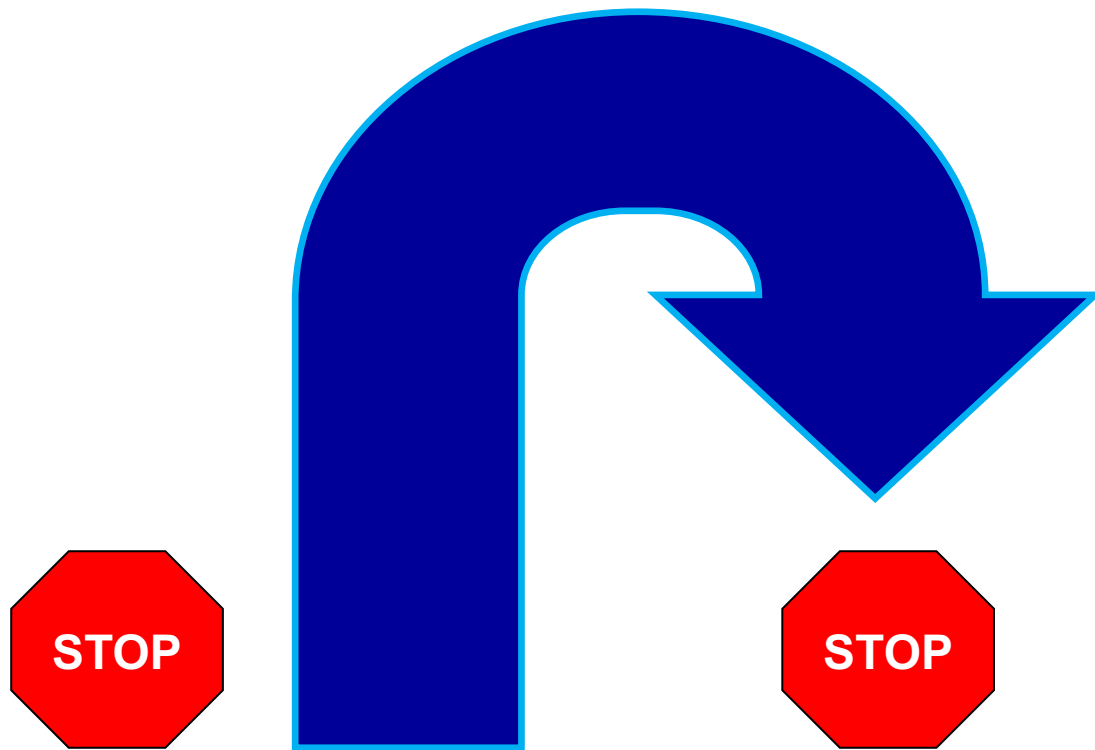




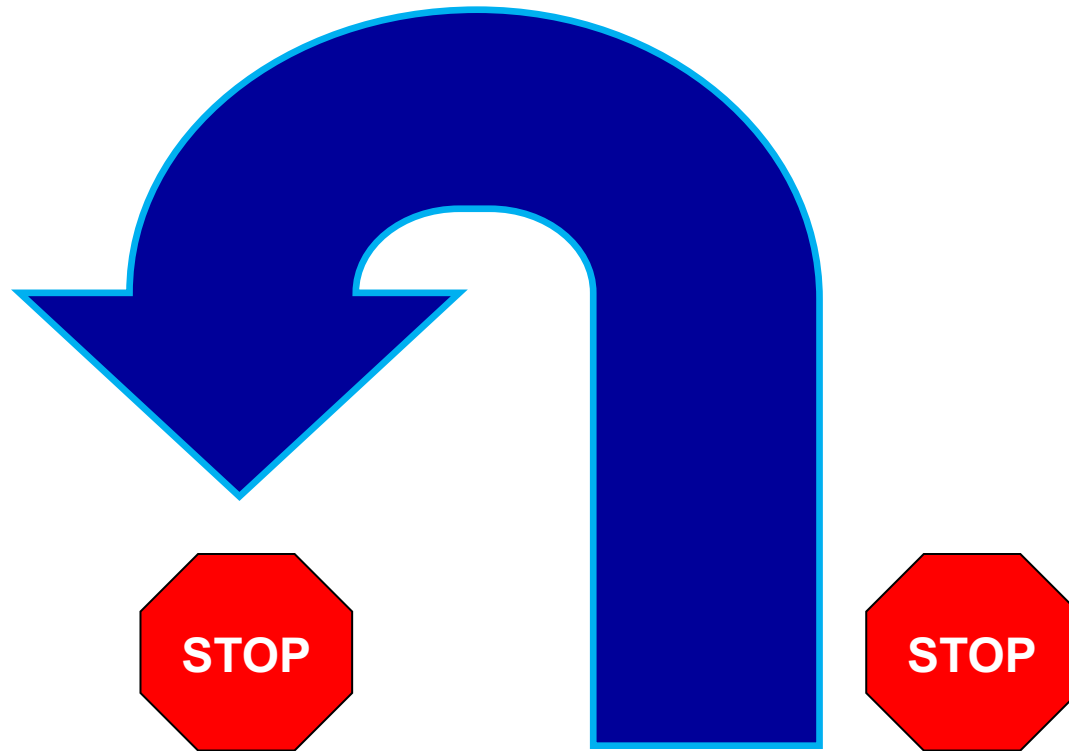
**180° RIGHT TURN
FORWARD**



**180° LEFT TURN
FORWARD**

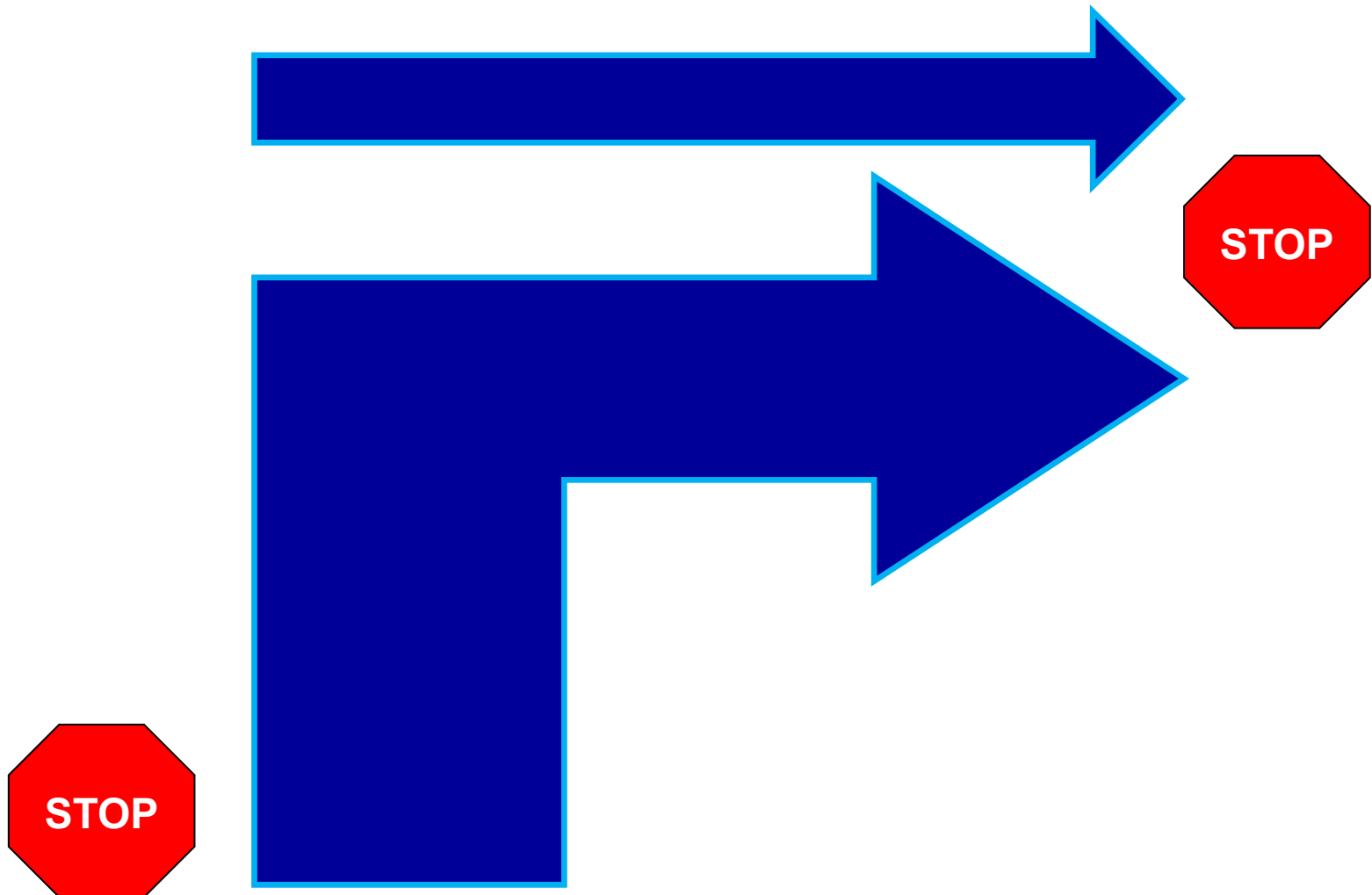


180° RIGHT TURN

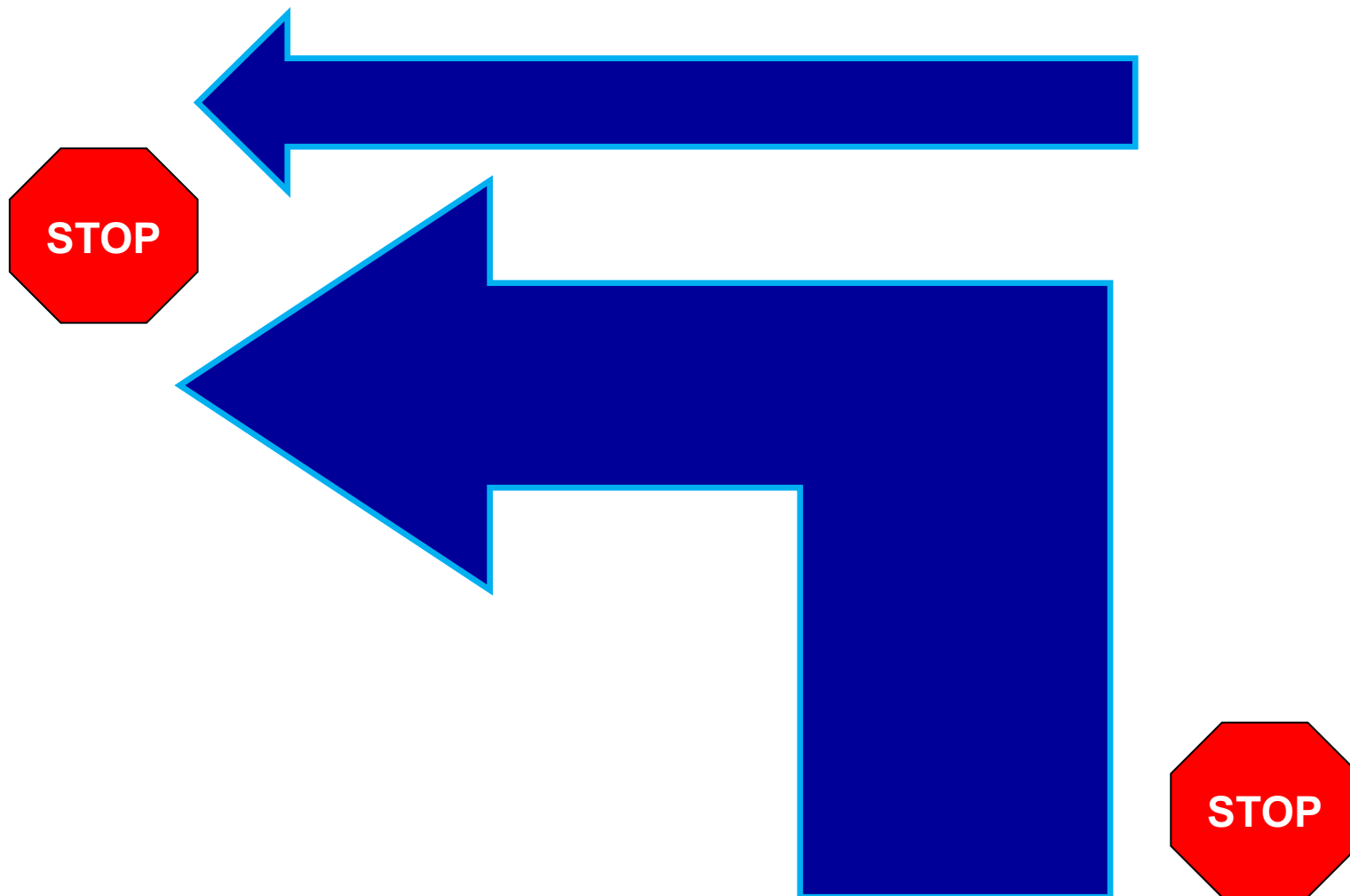


180° LEFT TURN

TURN RIGHT 1 STEP



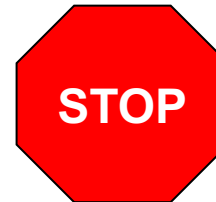
TURN LEFT 1 STEP



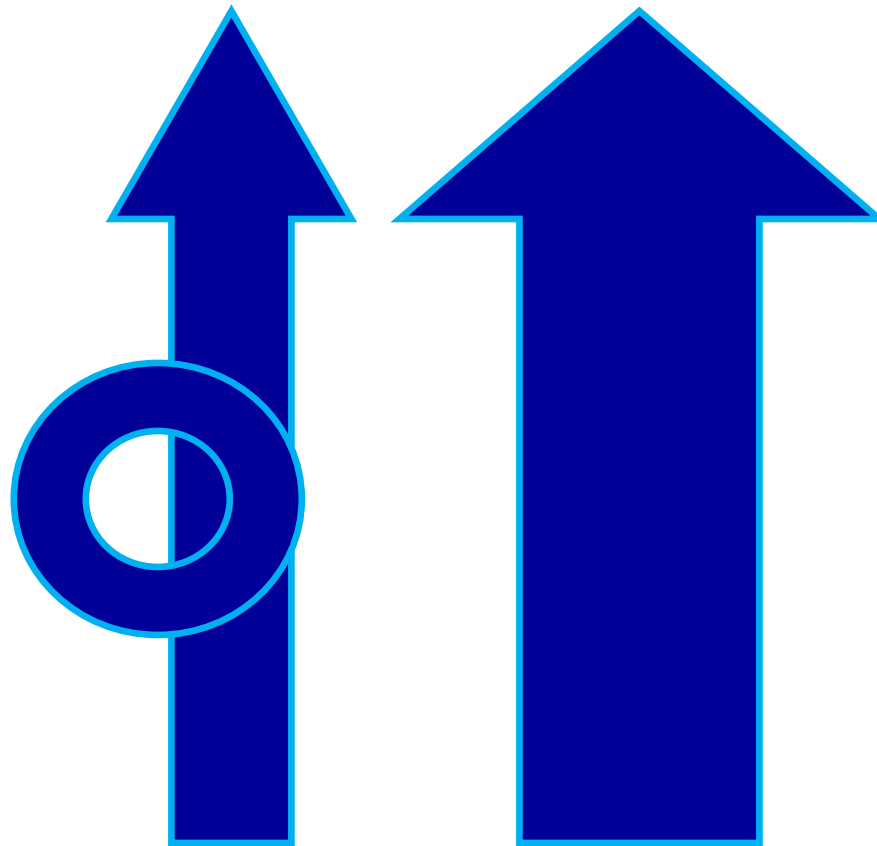


1 STEP STAND

2 STEPS

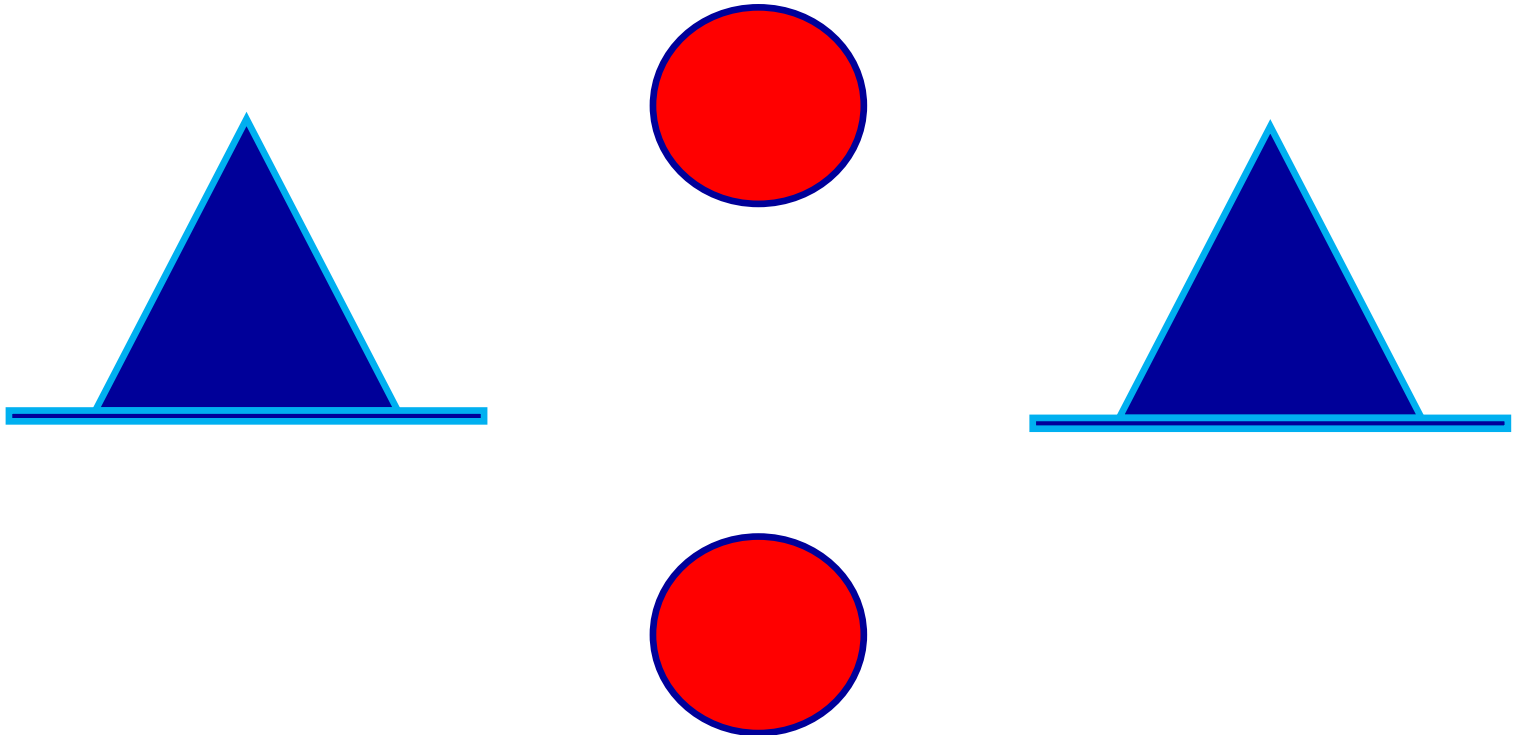


3 STEPS DOWN

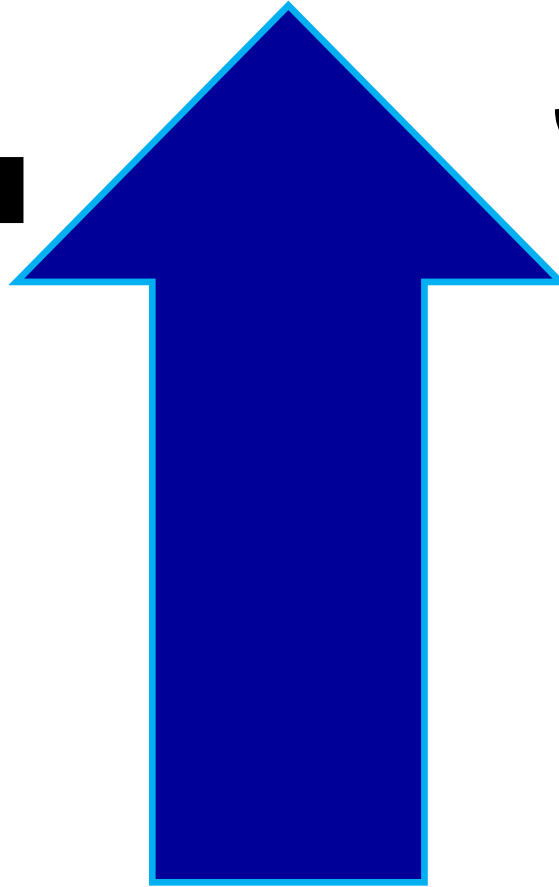
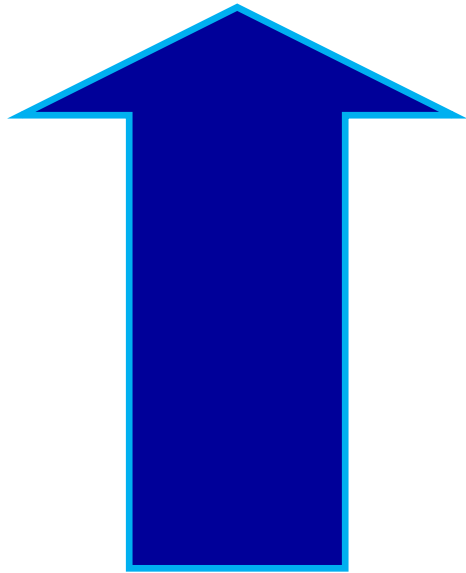


SPIN

DISTRACTIONS

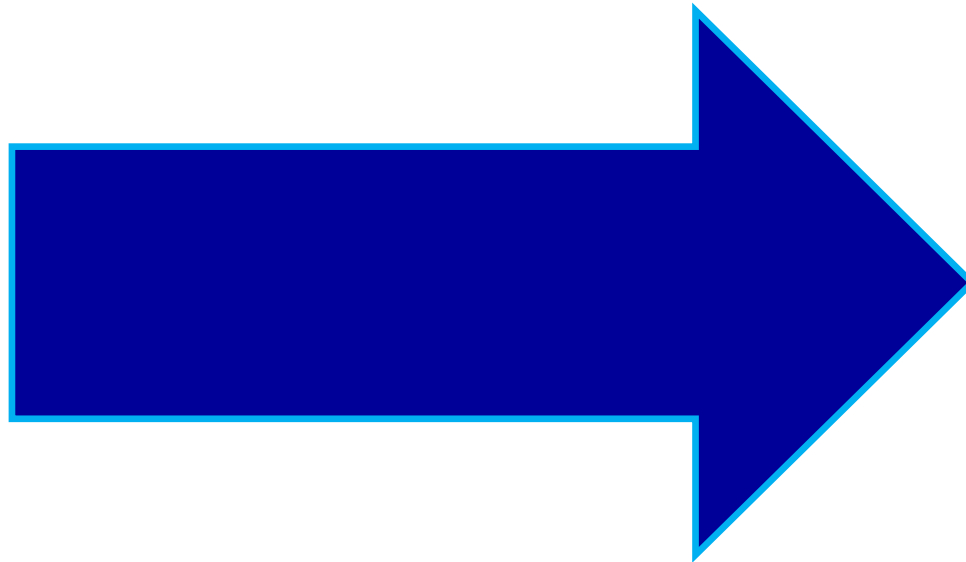


SEND OVER JUMP

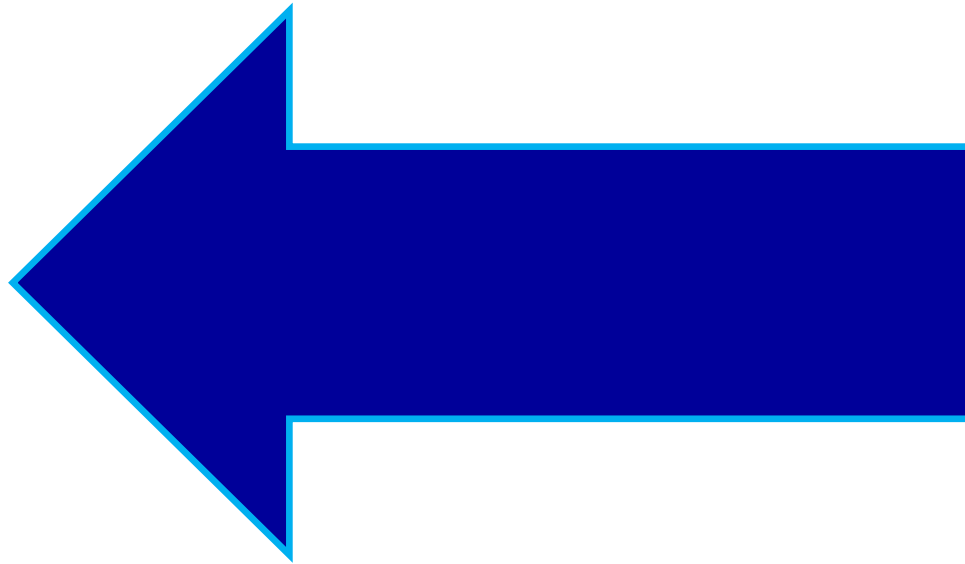


3 POINTS

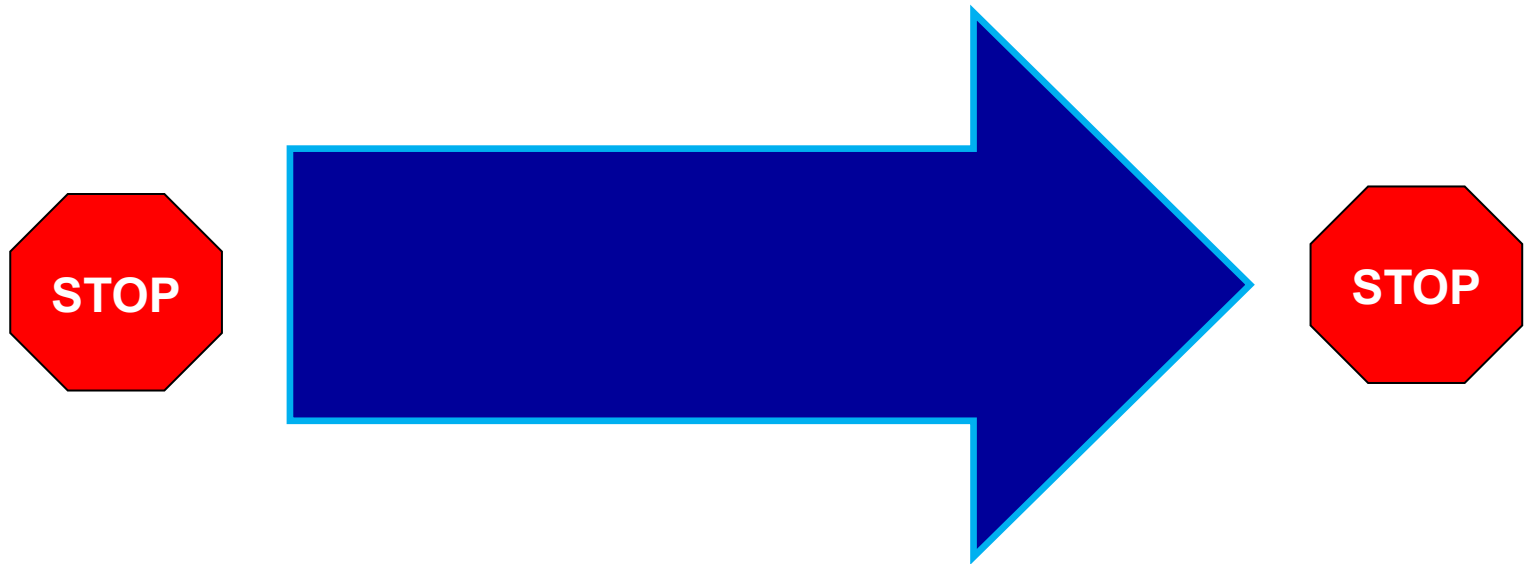
SIDE STEP RIGHT



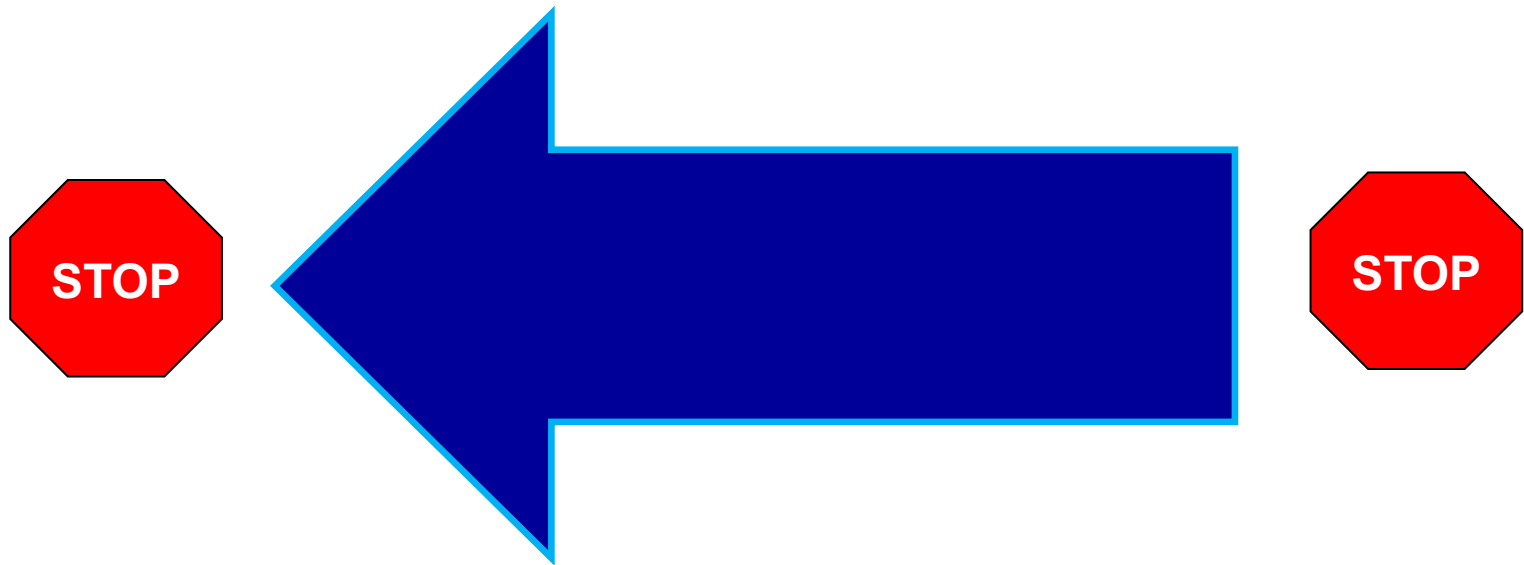
SIDE STEP LEFT

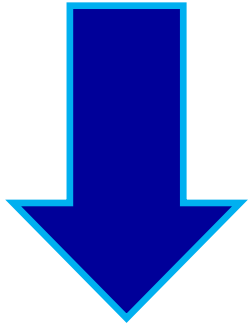


SIDE STEP RIGHT

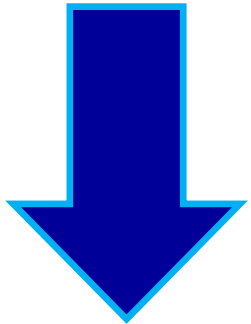


SIDE STEP LEFT



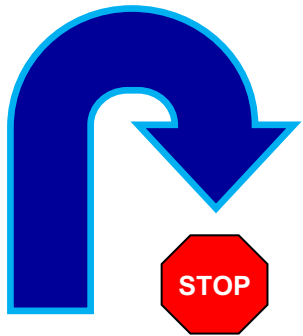


1 STEP BACK



2 STEPS BACK

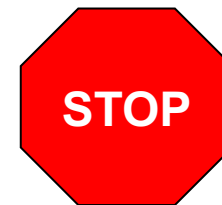




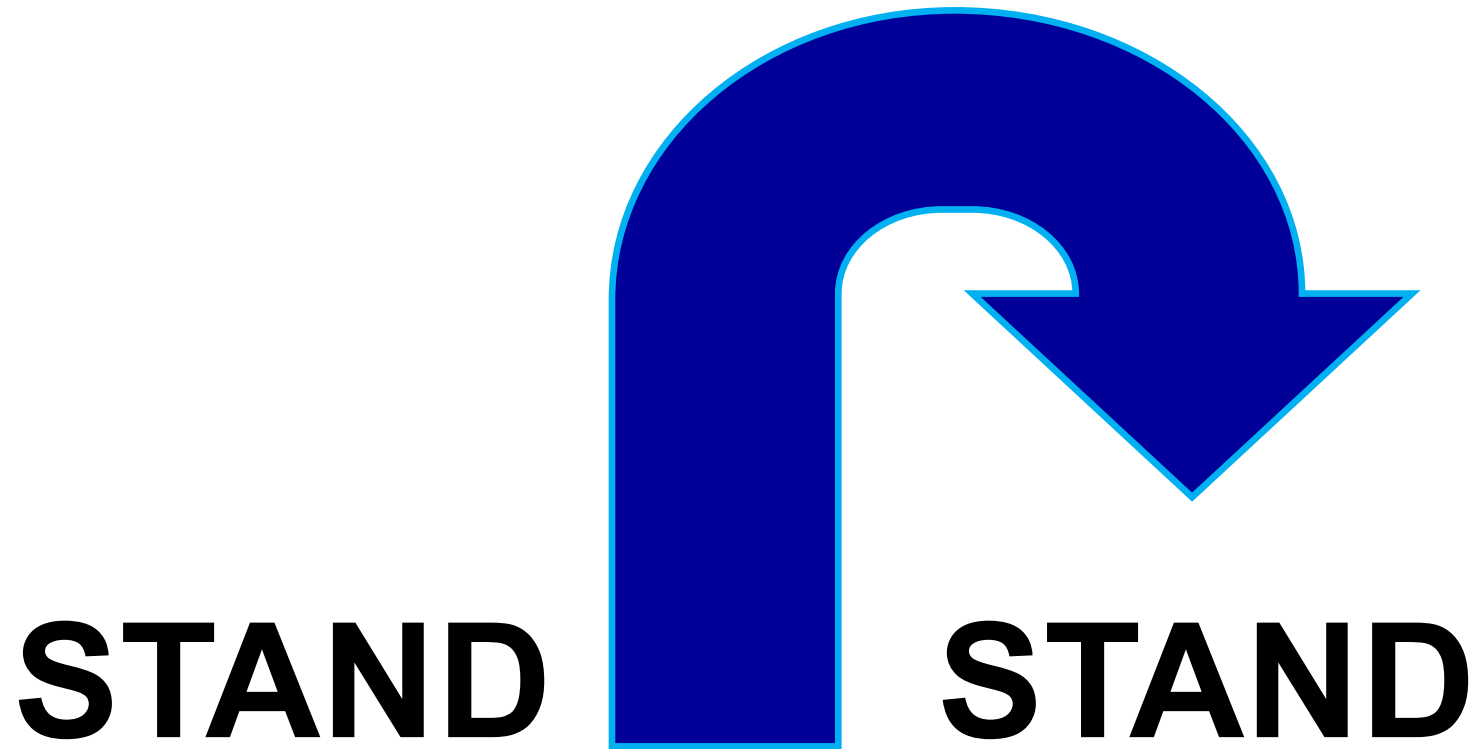
CALL FRONT

1 STEP BACK STAND

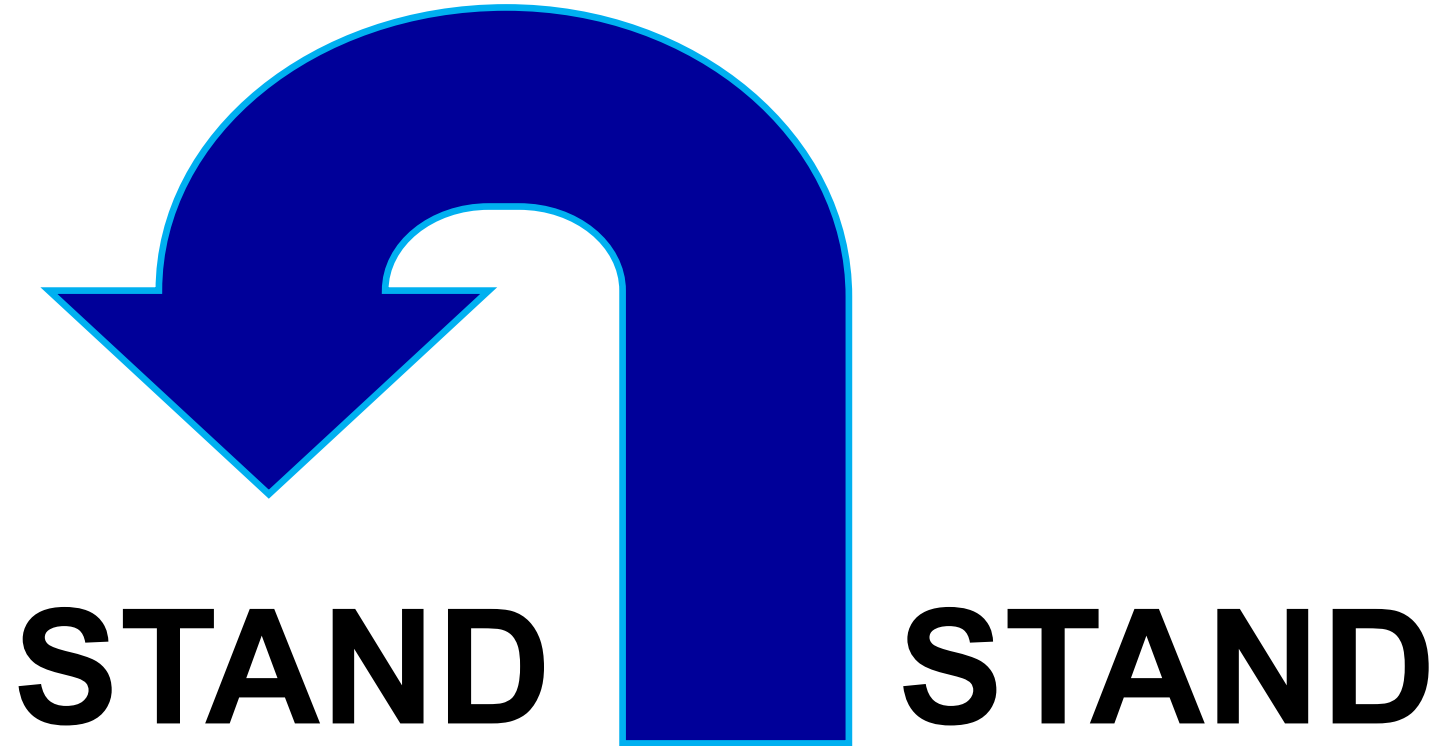
2 STEPS BACK



3 STEPS BACK DOWN

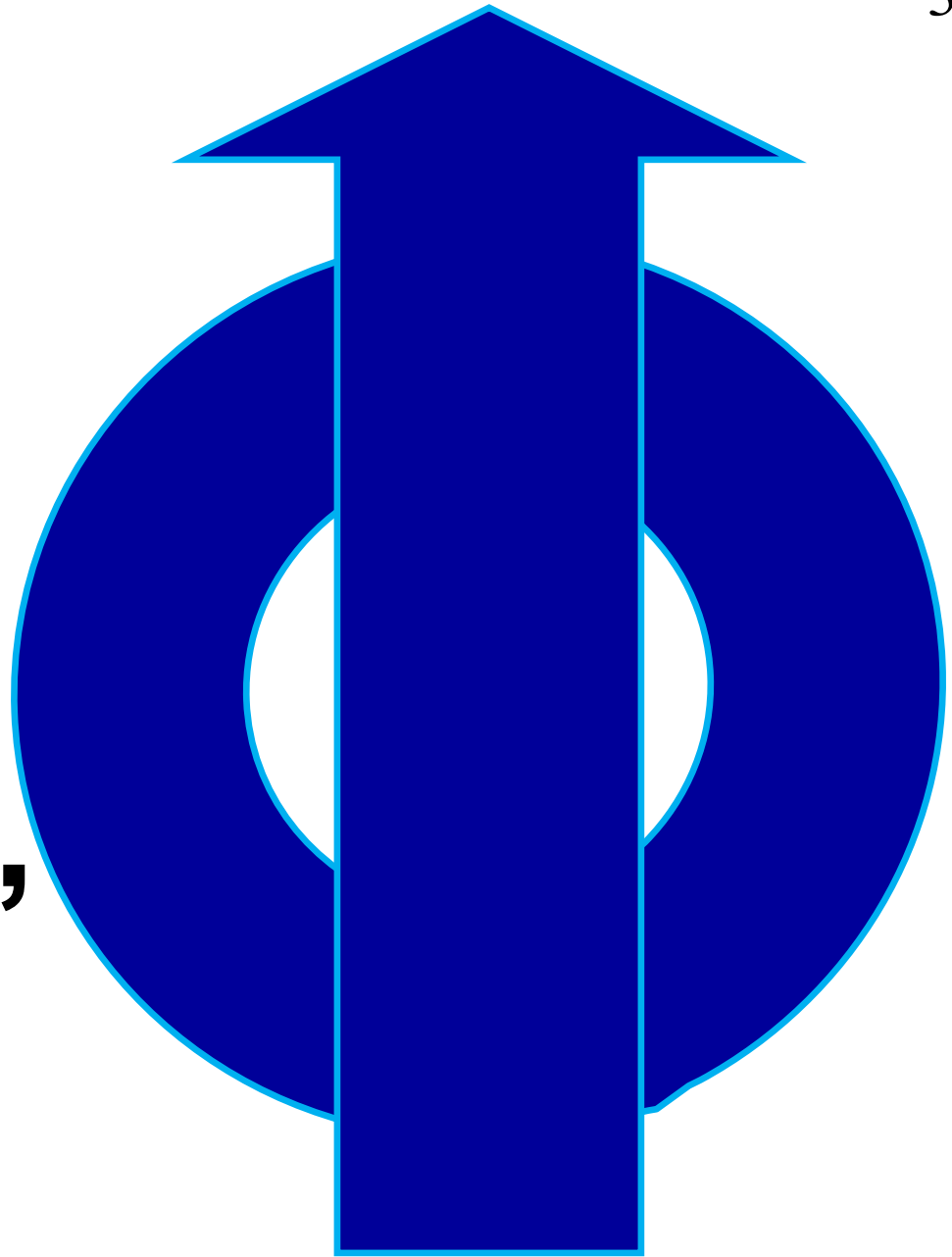


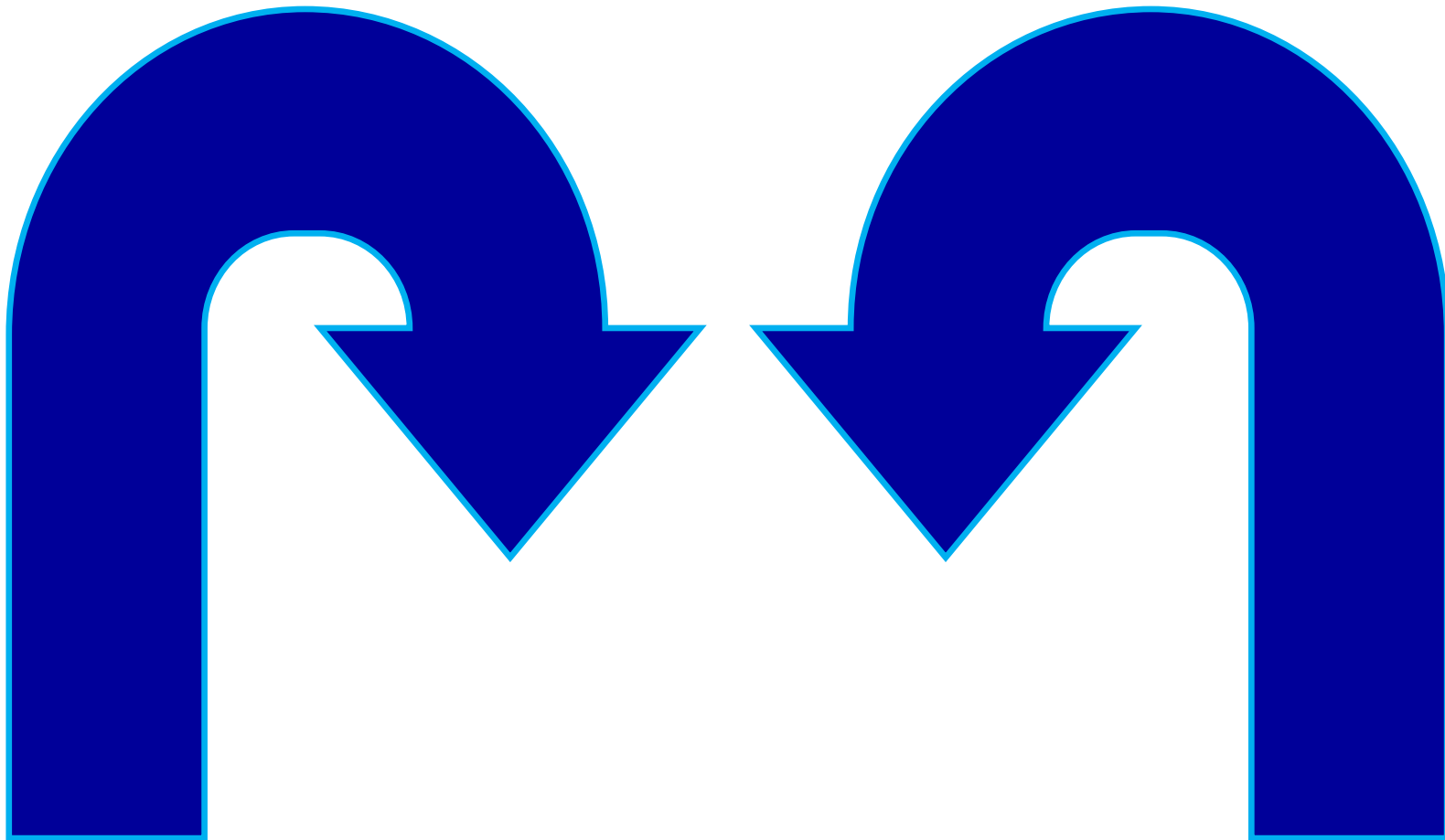
180° RIGHT TURN



180° LEFT TURN

**STAND,
CIRCLE
AROUND
HANDLER,
STAND**



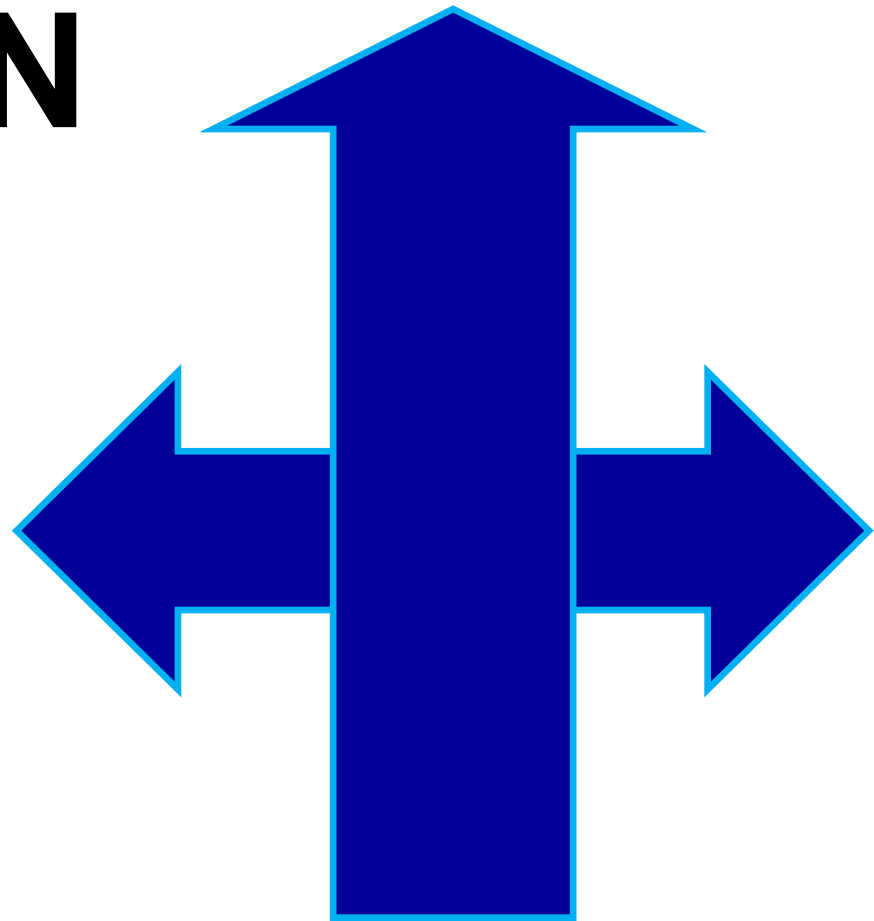


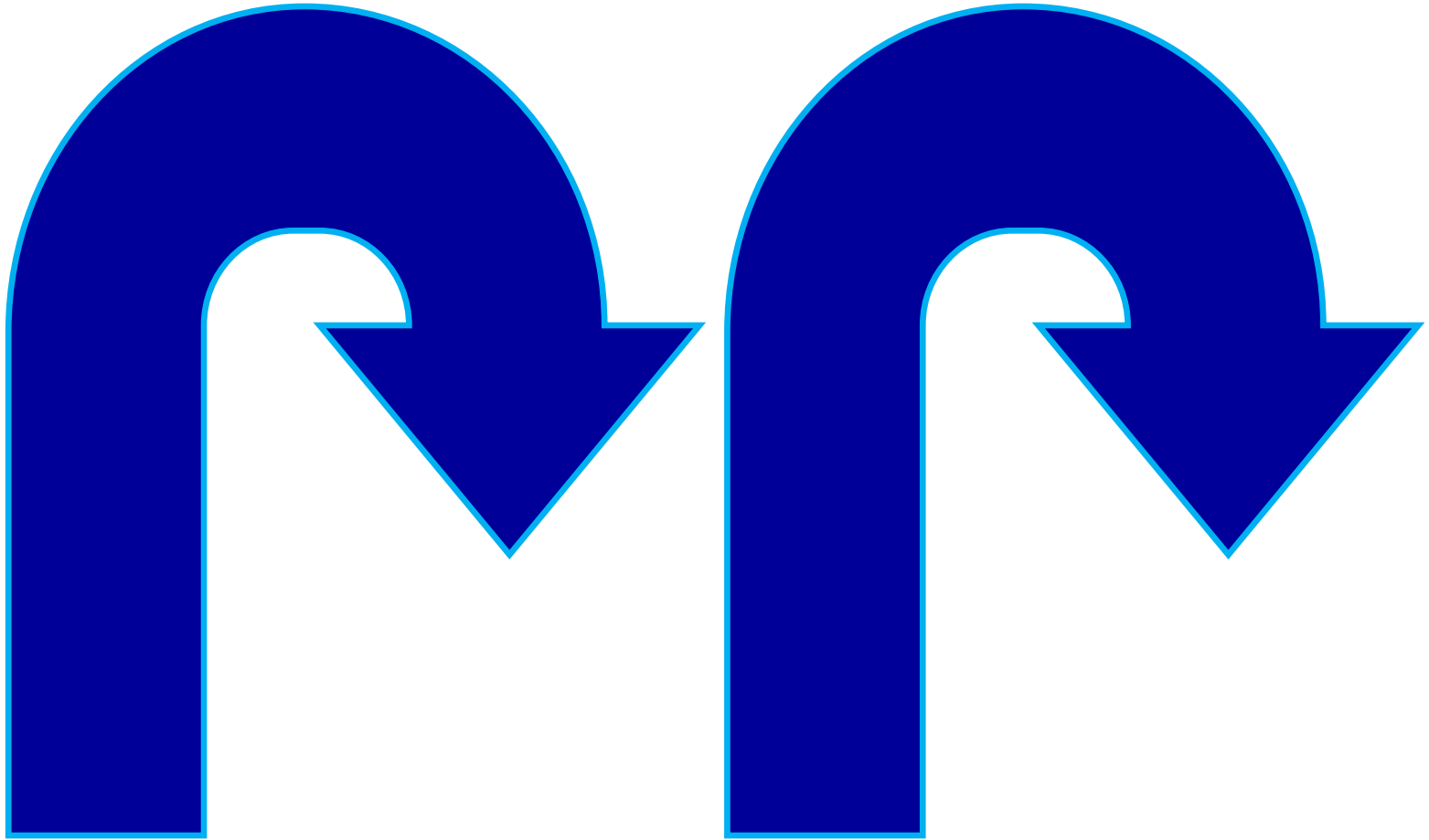
TURN TOWARD

SIDE SHIFT BEHIND

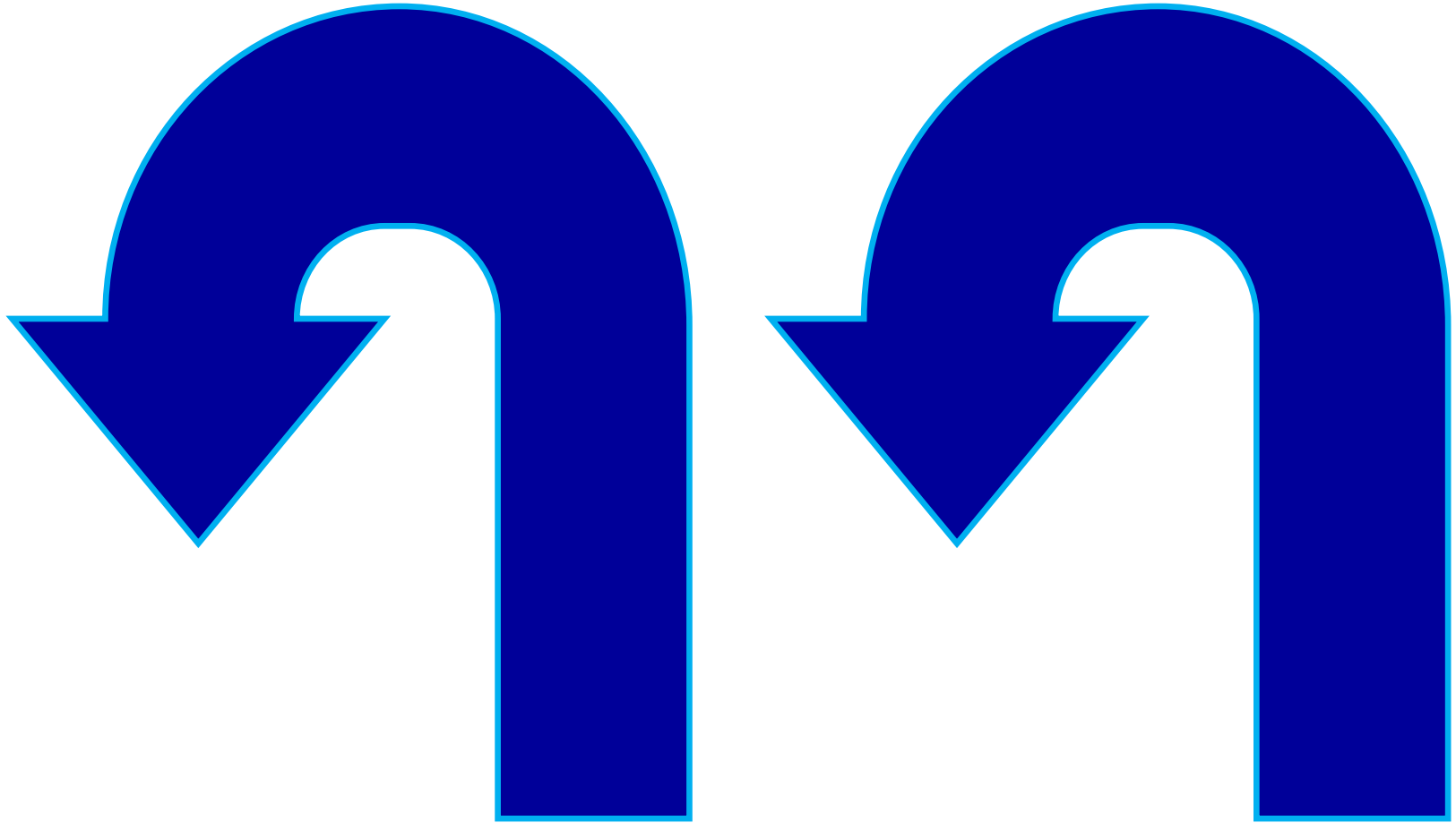


SIDE SHIFT BETWEEN LEGS



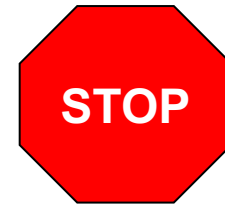


**BOTH ABOUT TURN
RIGHT**

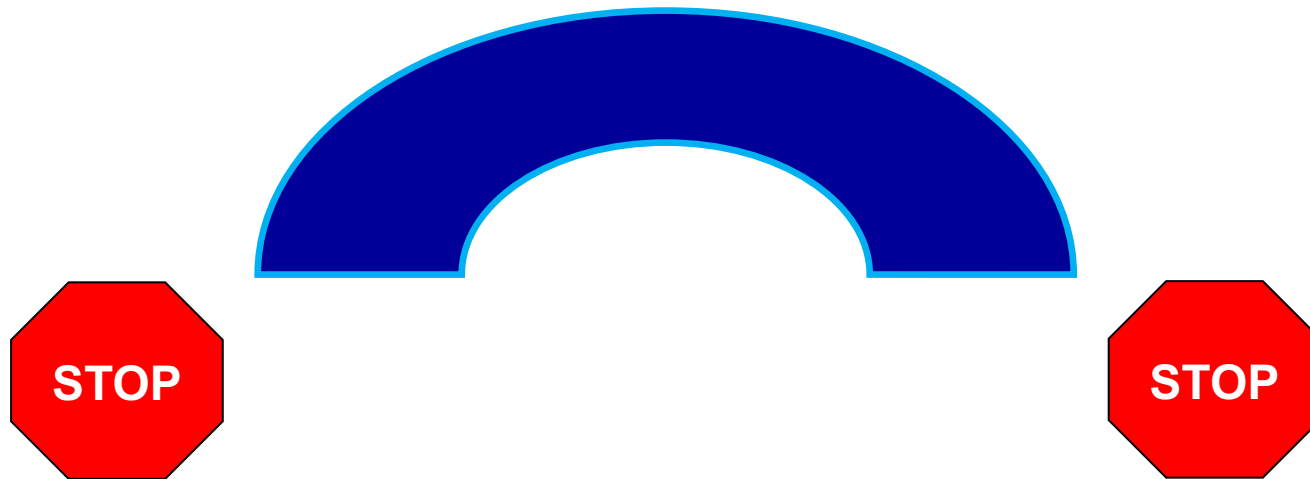


**BOTH ABOUT TURN
LEFT**

SIDE SHIFT BEHIND



SIDE SHIFT IN FRONT



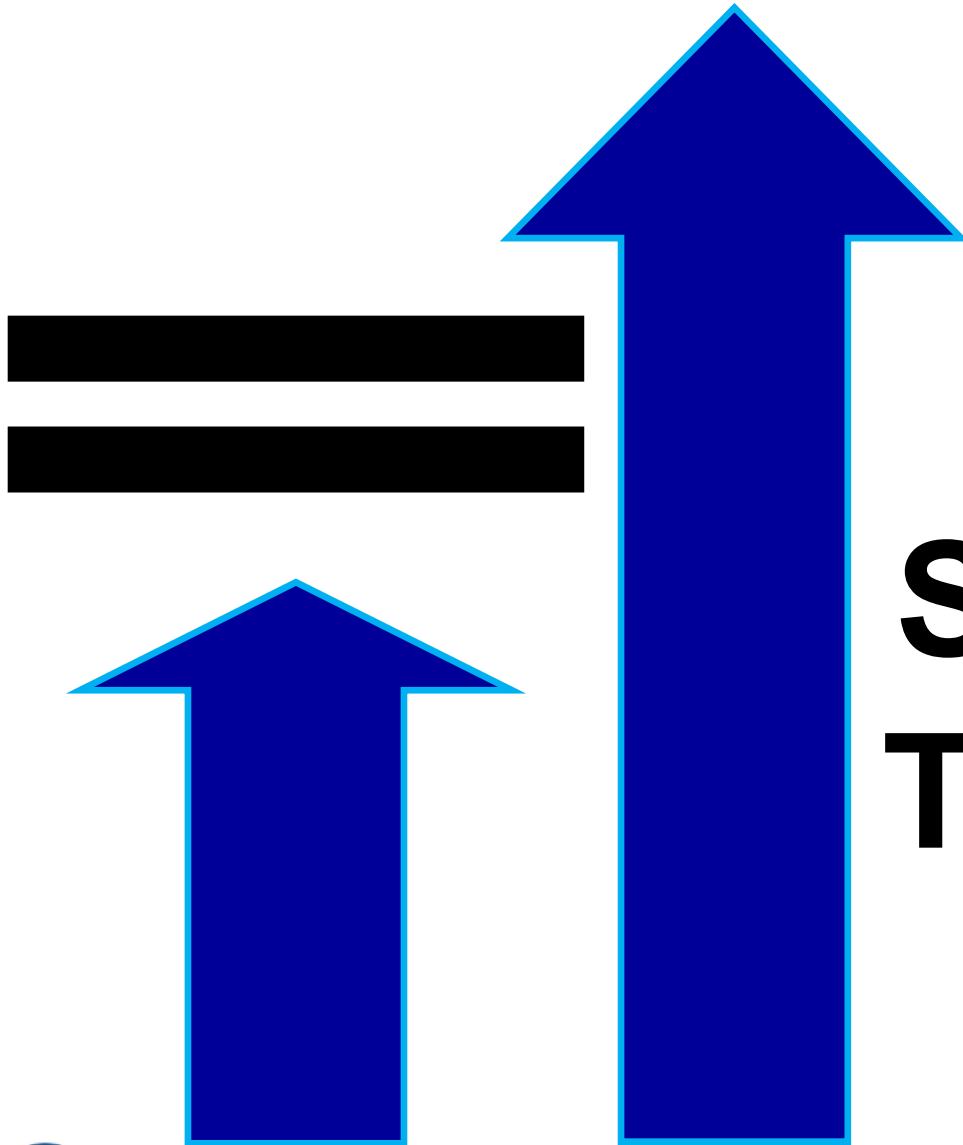


**MOVING STAND
WALK AROUND**

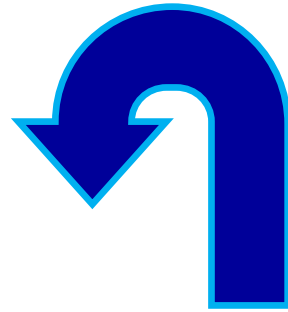


**MOVING DOWN
WALK AROUND**

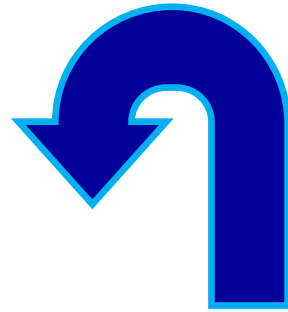




**SEND OVER
TWO JUMPS**



**TURN AROUND
RECALL**

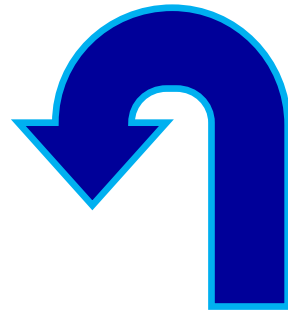


**TURN AROUND
RECALL FRONT**



RIGHT TO LEFT





**TURN AROUND
RECALL FRONT**

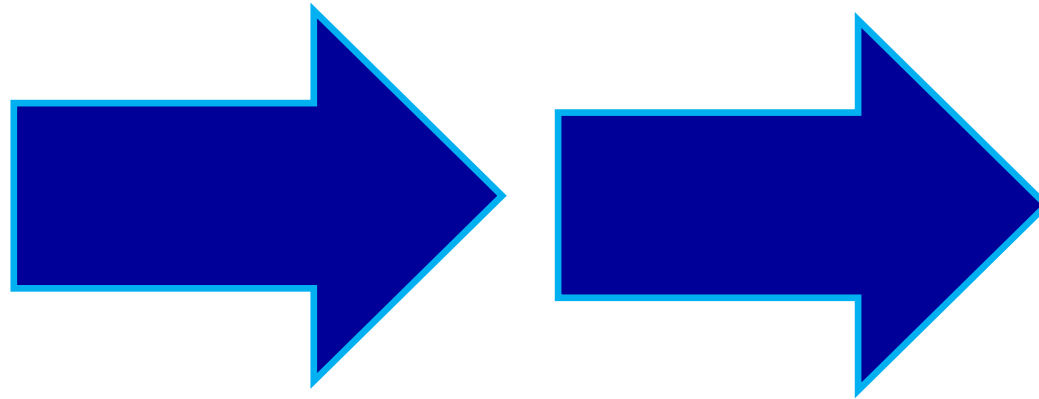


LEFT TO LEFT

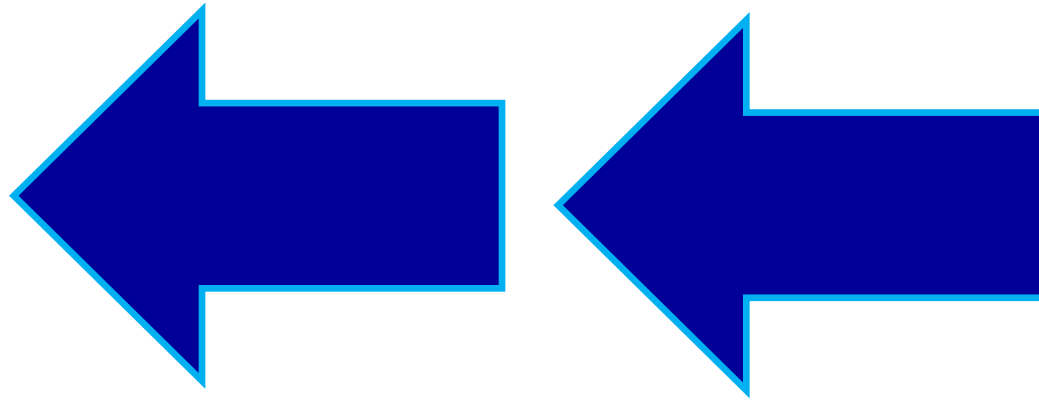


4 POINTS

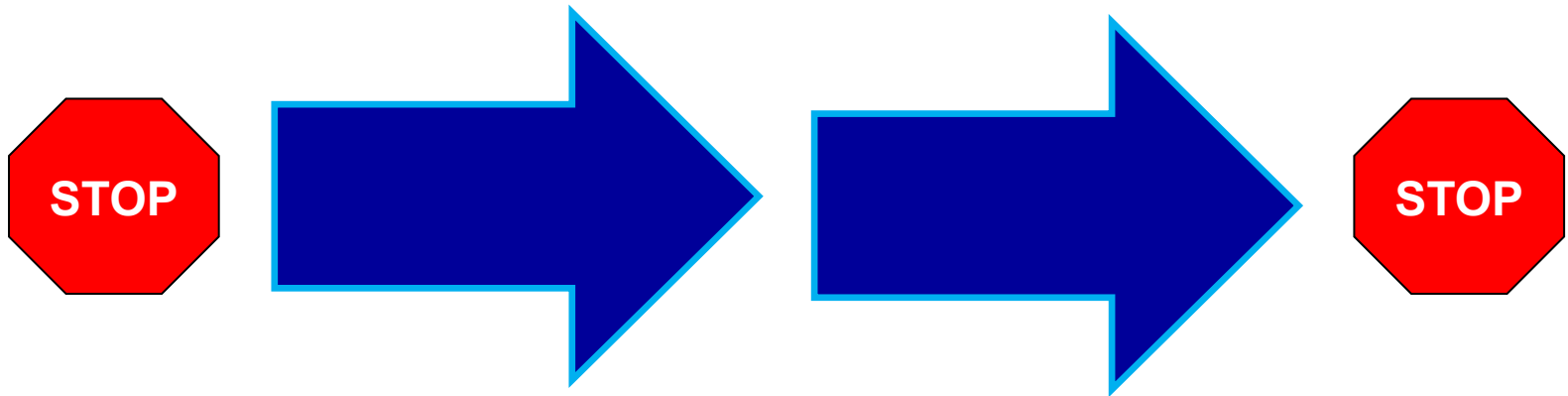
2 SIDE STEPS RIGHT



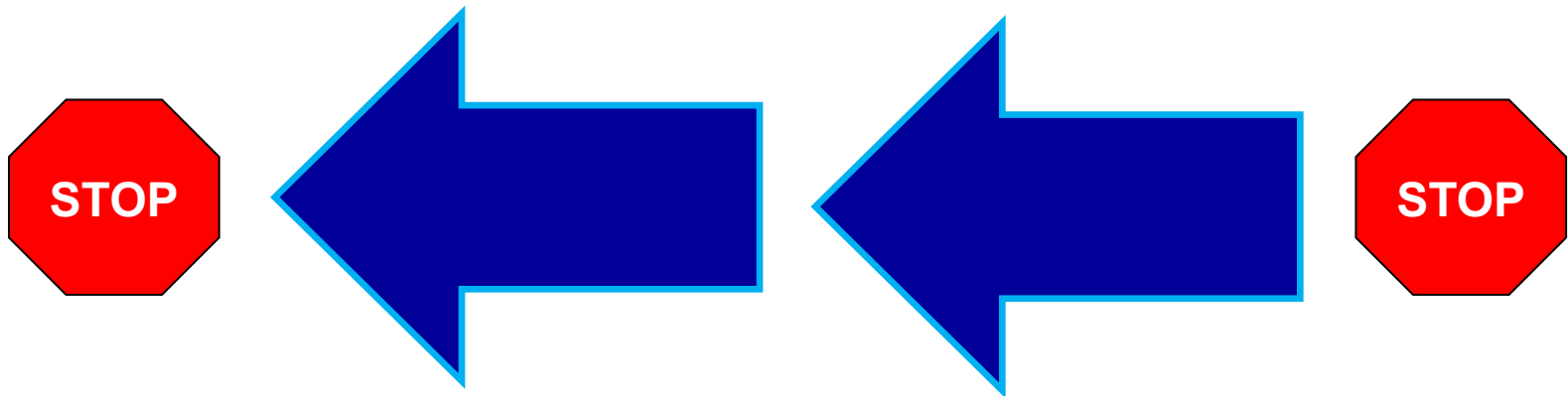
2 SIDE STEPS LEFT

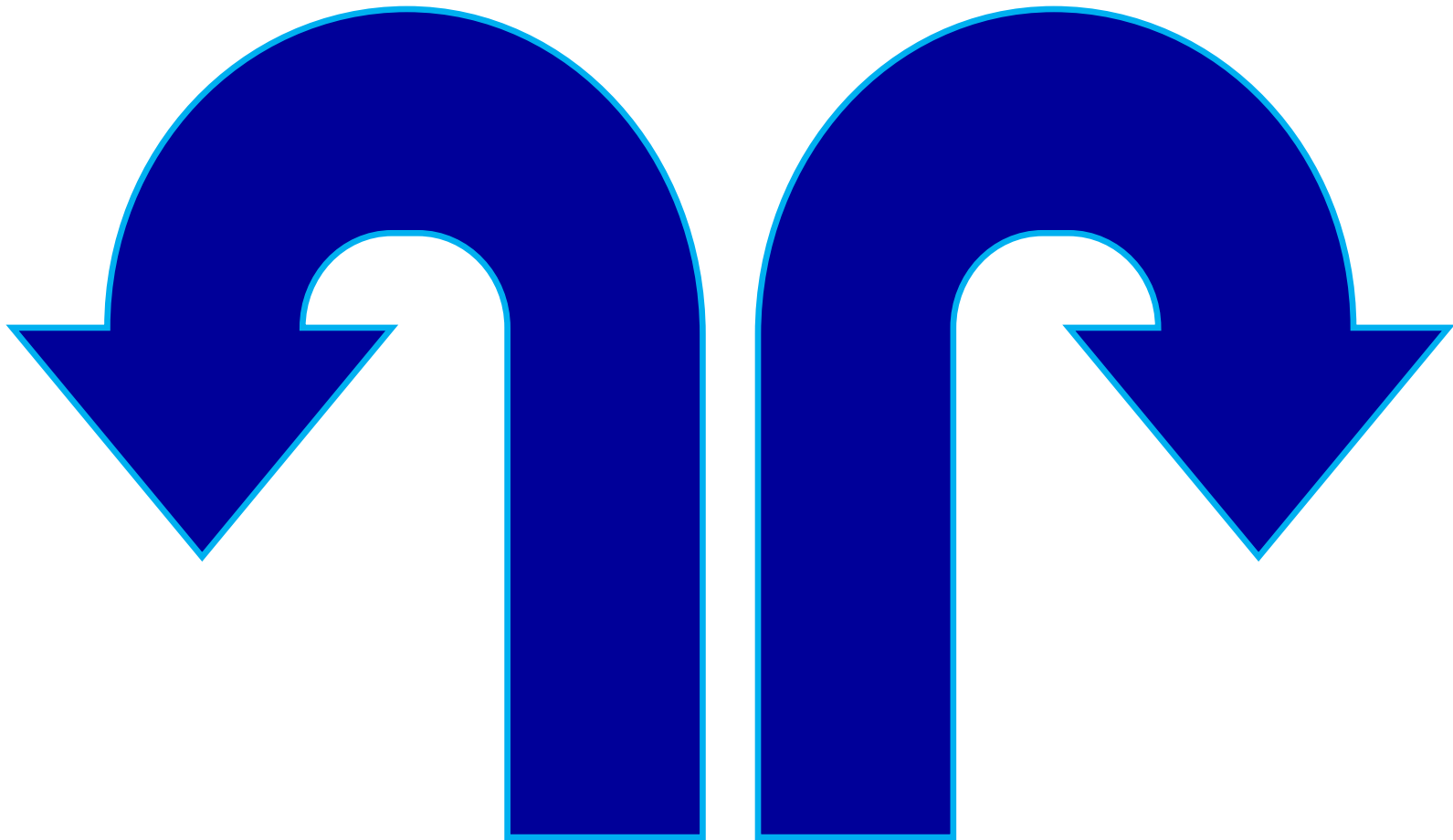


2 SIDE STEPS RIGHT



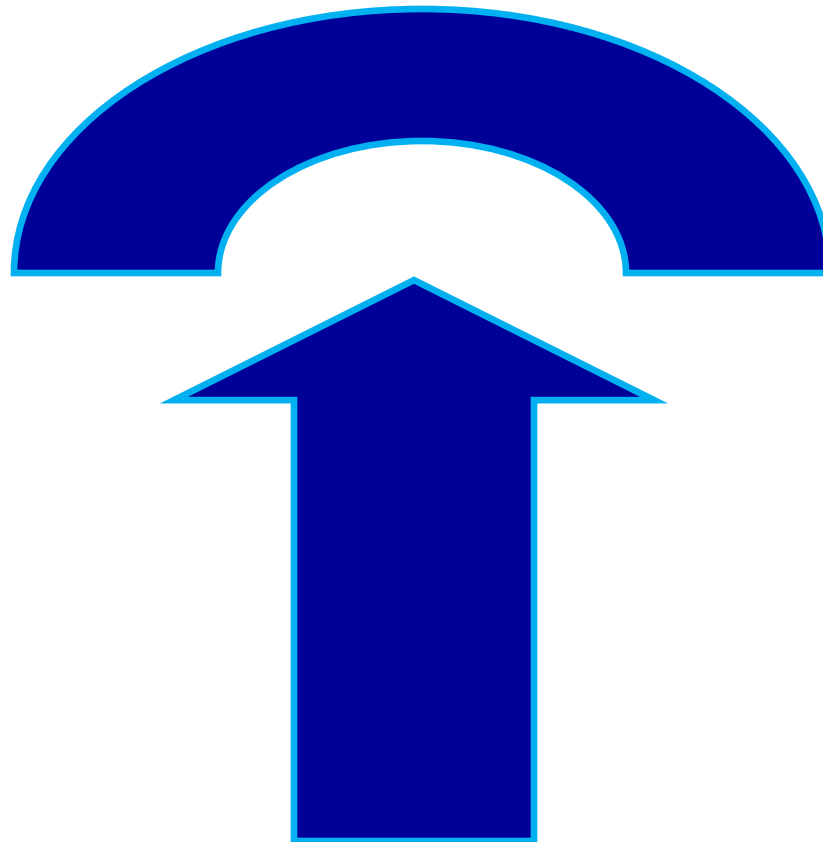
2 SIDE STEPS LEFT



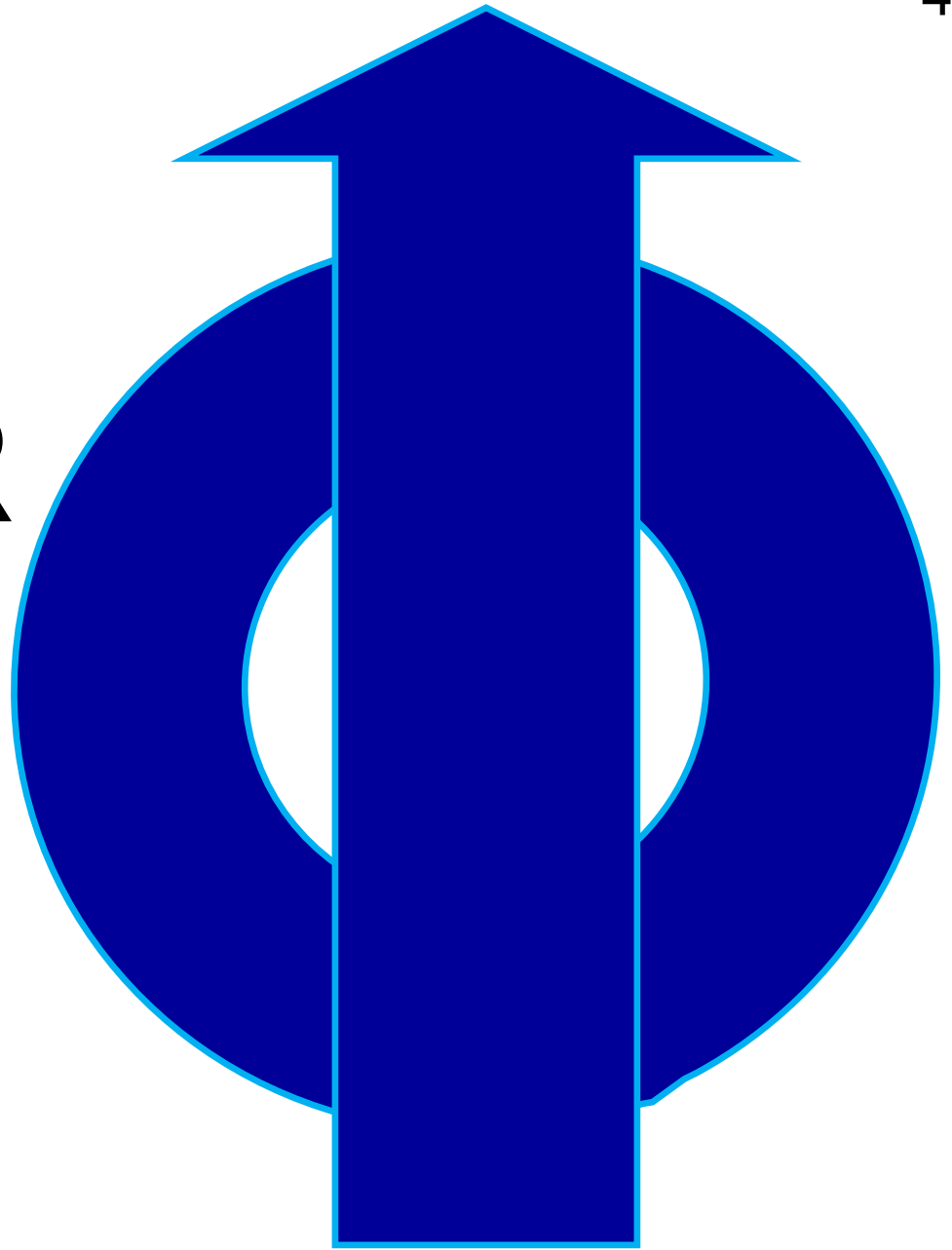


TURN APART

SIDE SHIFT IN FRONT



CIRCLE AROUND HANDLER

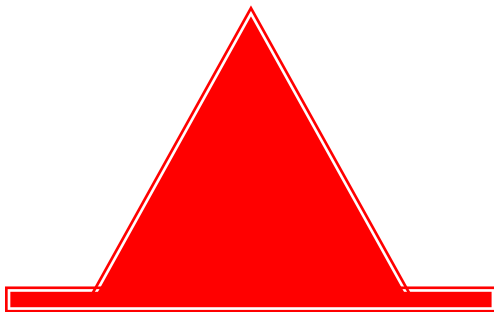




**MOVING SIT
WALK FORWARD**

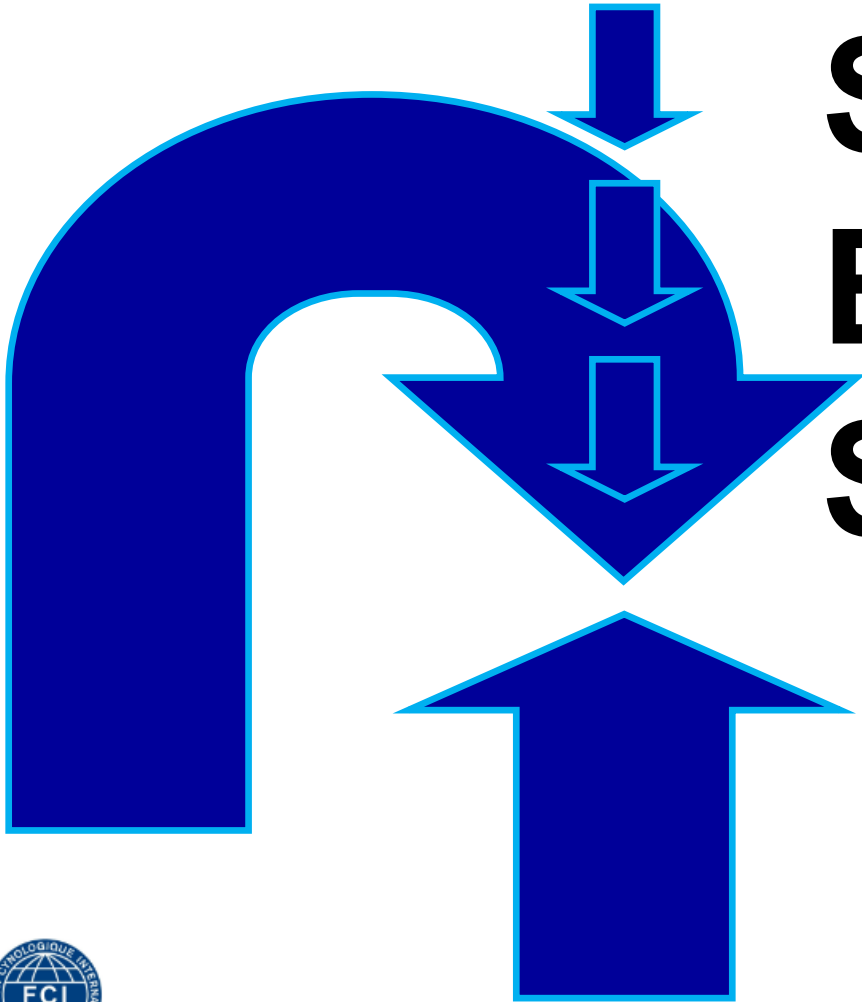


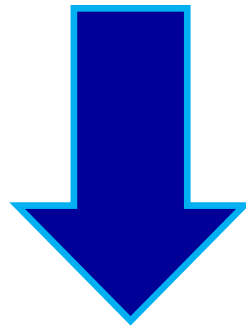
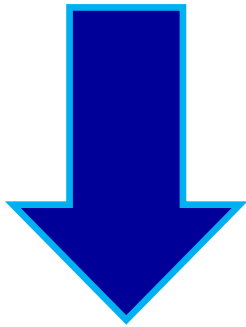
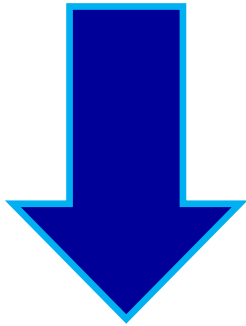
**MOVING DOWN
WALK FORWARD**



**SEND AWAY
STAND**

**CALL FRONT
STAND
BACK AWAY
STAND**





BACKWARDS

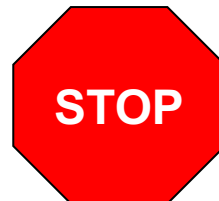
3 STEPS



1 STEP BACK STAND

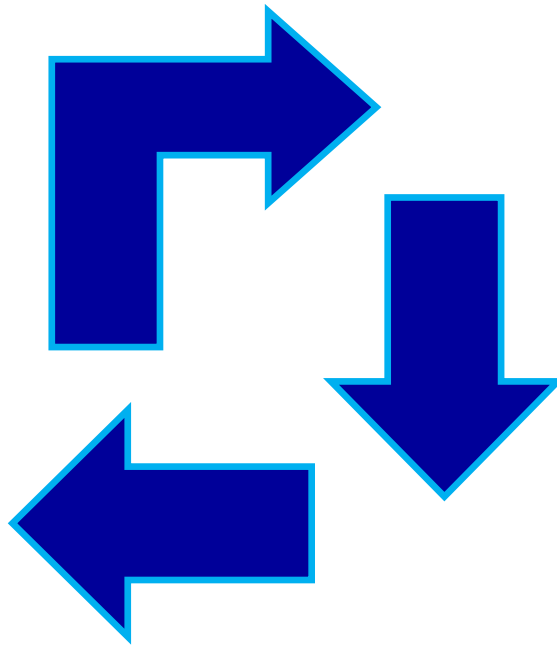


2 STEPS BACK



3 STEPS BACK DOWN



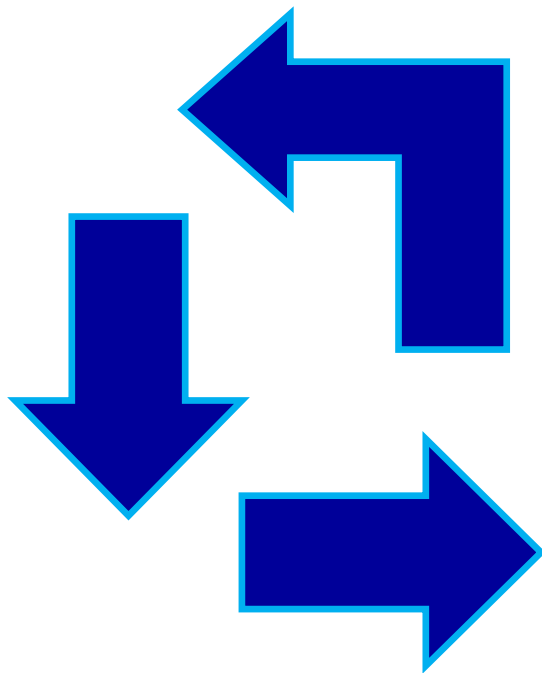


90° TURN RIGHT STAND

90° TURN RIGHT



90° TURN RIGHT DOWN



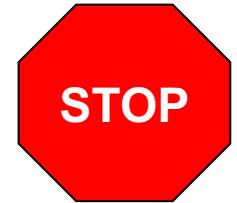
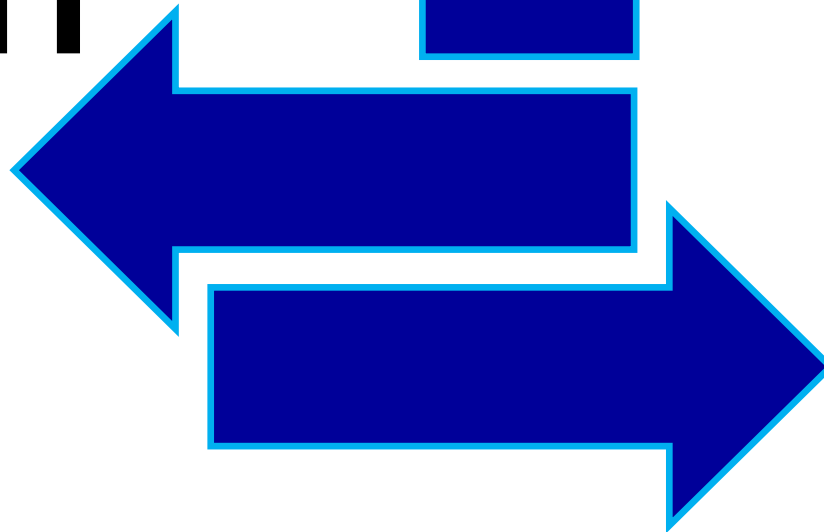
90° TURN LEFT STAND

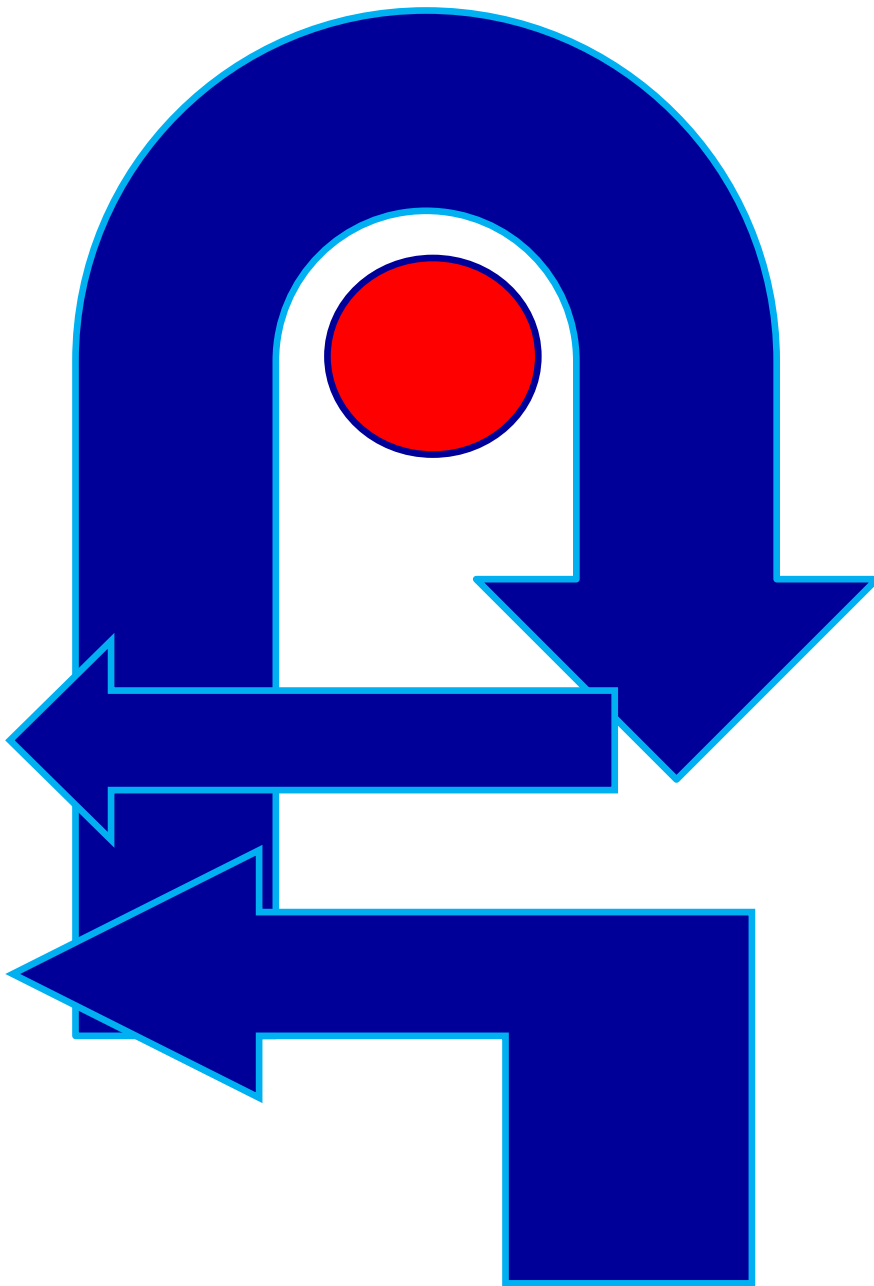
90° TURN LEFT



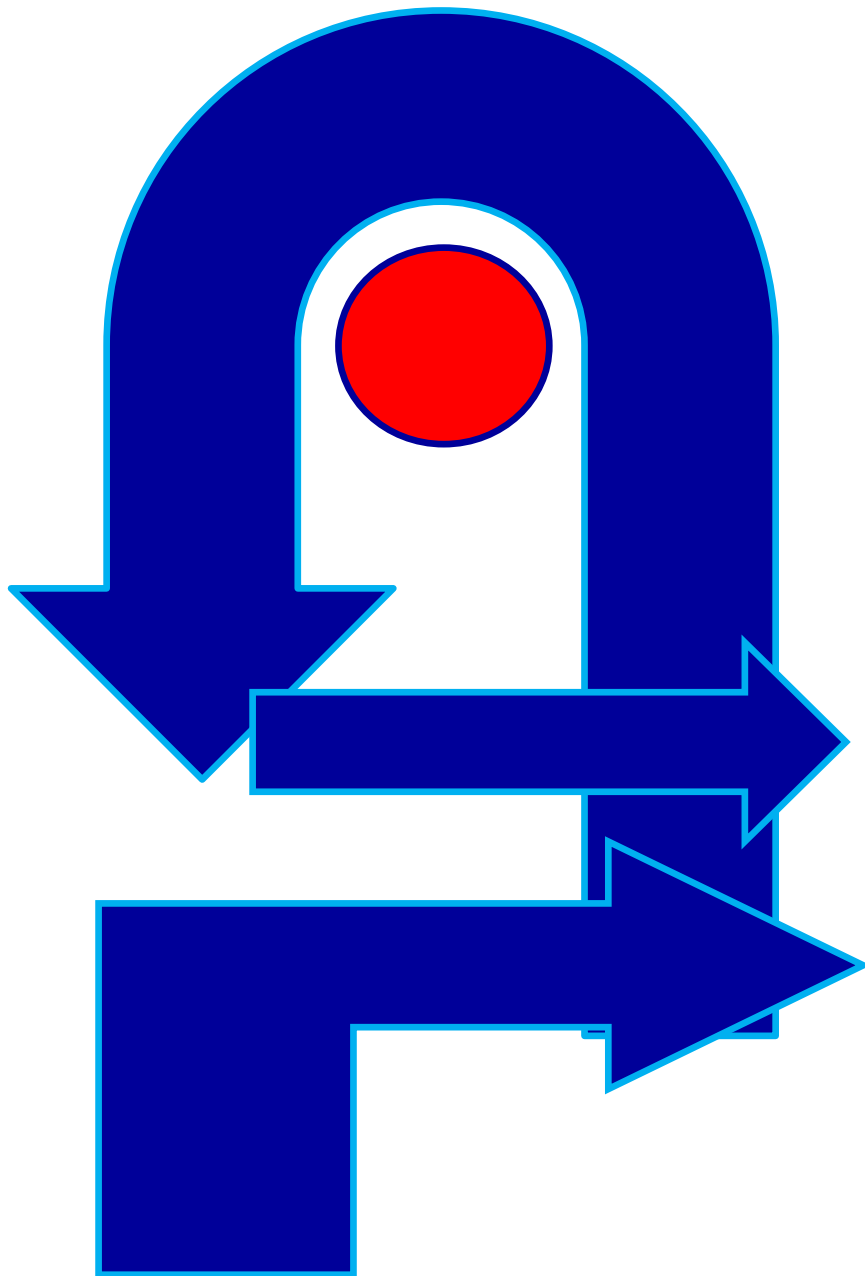
90° TURN LEFT DOWN

**CALL FRONT
SIDE STEP
LEFT
SIDE STEP
RIGHT**





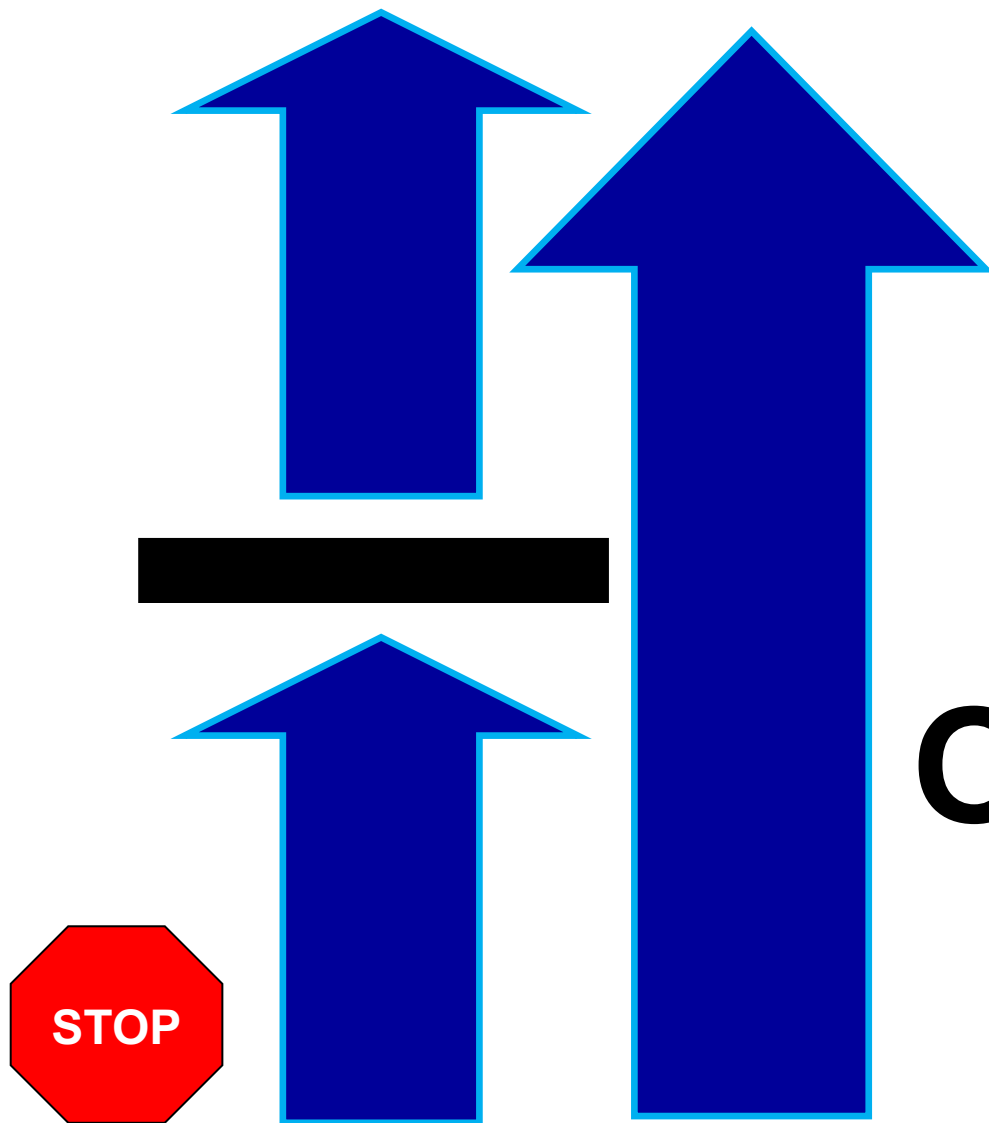
**90° TURN
LEFT
AROUND
CONE**



**90° TURN
RIGHT
AROUND
CONE**



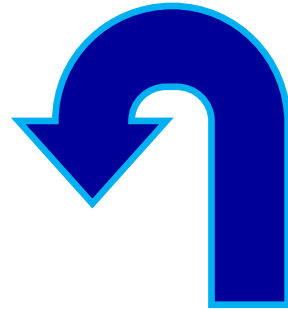
**MOVING SIT
WALK AROUND**



**RECALL
OVER JUMP**

TURN AROUND RECALL OVER JUMP





**TURN AROUND
BACK AWAY**



**DOWN
RECALL**